

## **CORRELATION WIND LIDAR WITH PMT DETECTOR ARRAY & PHOTON-COUNTING: TEST BED RESULTS**

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# TITLE: TALK OUTLINE

1. Background
2. The lidar concept
3. The ground lidar test system
4. Data format & pre-processing
5. The Winds
6. Conclusions & Outlook
7. Acknowledgments

# BACKGROUND

- > Atmospheric Winds: very important parameter for many applications: Meteorology, Climatology, Atmospheric research, Navigation, ...
- > Wind measurement techniques:
  - # **DWL**: Detect Frequency change of Doppler shift (as in Aeolus Satellite, ESA since 2018 ...)
  - # **PBL** winds via Auto-Correlation of Aerosol inhomogeneities with (ground)scanning Elastic lidar (Eloranta, University Wisconsin, 1977)
  - # **Cloud image** correlation : first Wind measurements with correlation from satellites (NOAA, 1970)

## BACKGROUND #2

DWL Technique (Aladin Instrument on Aeolus Satellite) is the best in terms of altitude range (0- 30 km), resolutions, accuracy but:

- > DWL Tx requirements: very demanding in terms of wavelength, spectral purity, stability & energy
- > DWL Rx requirements: high frequency accuracy/stability of filtering, very complex focal plane detection & processing

>>**This work: Simpler system based vector-wind determination by X-correlation of Matrices of Elastic-Lidar-generated Point Clouds (0-10 km) + proposal x combination of Passive O<sub>2</sub> Doppler Interferometer in Limb Sounding, for Molecular winds (10-30 km)**

# THE LIDAR CONCEPT

## § Tx lidar based on:

- # High-repetition rate (KHz), IR/Vis low energy , multi-beam laser
- >> Vastly simplified laser technology & relaxed requirements than for DWL

## § Rx lidar based on:

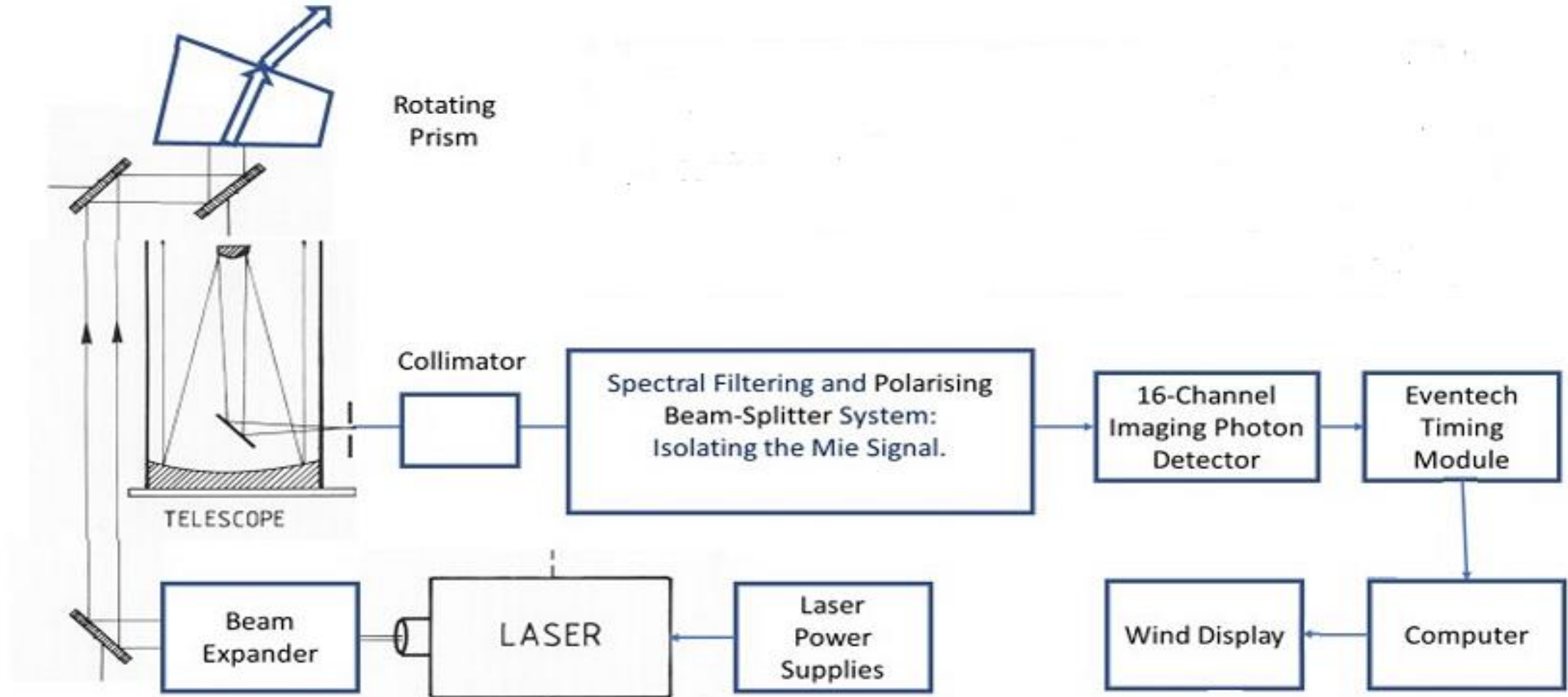
- # Single Photon Detection/Counting with multi-channel PMT array
- # Cross-correlation of Point-Cloud Images of Tropospheric aerosols
- >> Vastly simplified Rx requirements than for DWL

## § Multi-functional idar concept:

- # High on Processing & Computer Power, apt for Sensor Data Fusion

# Ground Validation Test Bed

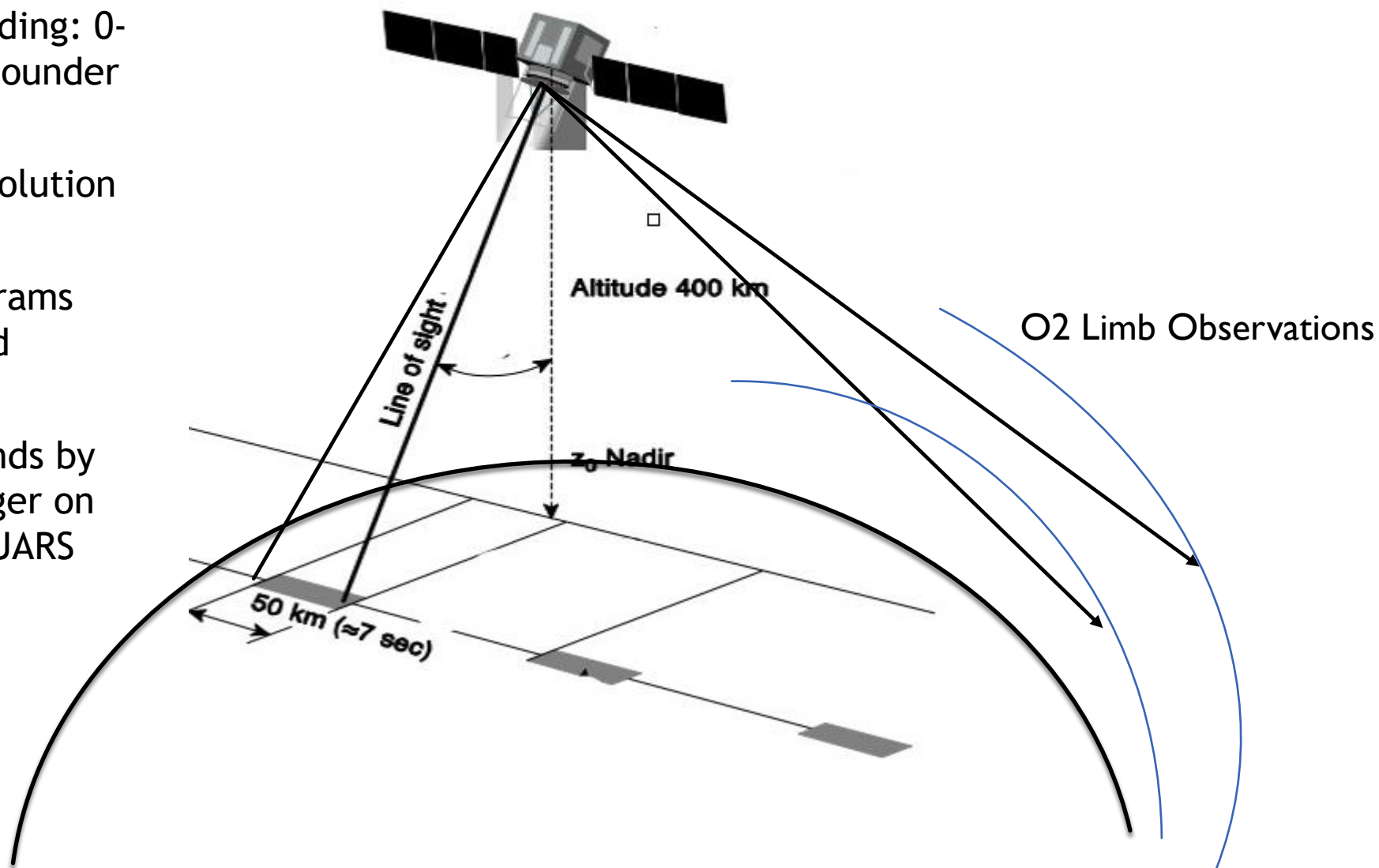
## □ CORRELATION WIND LIDAR CONFIGURATION





# WIND SATELLITE SPACE CONCEPT

- Combo-Instrument Satellite: CWL + Doppler Imager in Limb Sounding: 0-10 km CWL, 10-30 km Limb Sounder
- CWL emits 2 beams spatially separated by  $dx < \text{spatial resolution}$  (50 km), at an angle:  $\delta\phi$
- CWL: 0-10 Km aerosol histograms correlation provides 2-D wind components
- Limb Sounder: 10-30 Km: winds by High Resolution Doppler Imager on O<sub>2</sub> lines (already proven on UARS HRDI)



# The CWL Engine

## Left View:

Tx Laser (TEEM multi-mode, Un-stabilized, ~20  $\mu$ J\*, 1 KHz, 20 mW, @ 355 nm), beam-expander, Newport Scanner & scan mirror mount.

(\* ) before degradation of 2<sup>nd</sup> & 3<sup>rd</sup> harmonic filters to below 10  $\mu$ J

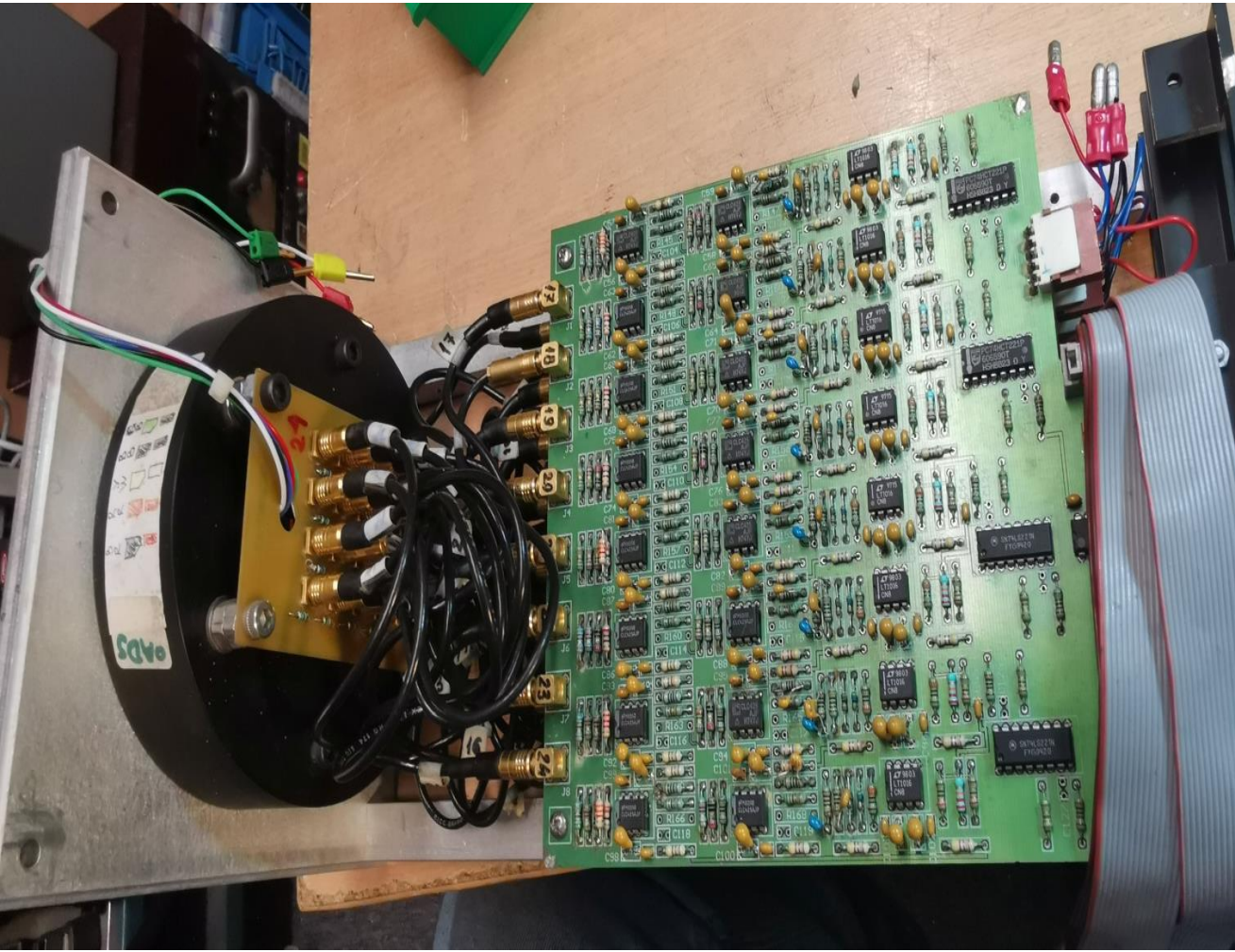


## Right View:

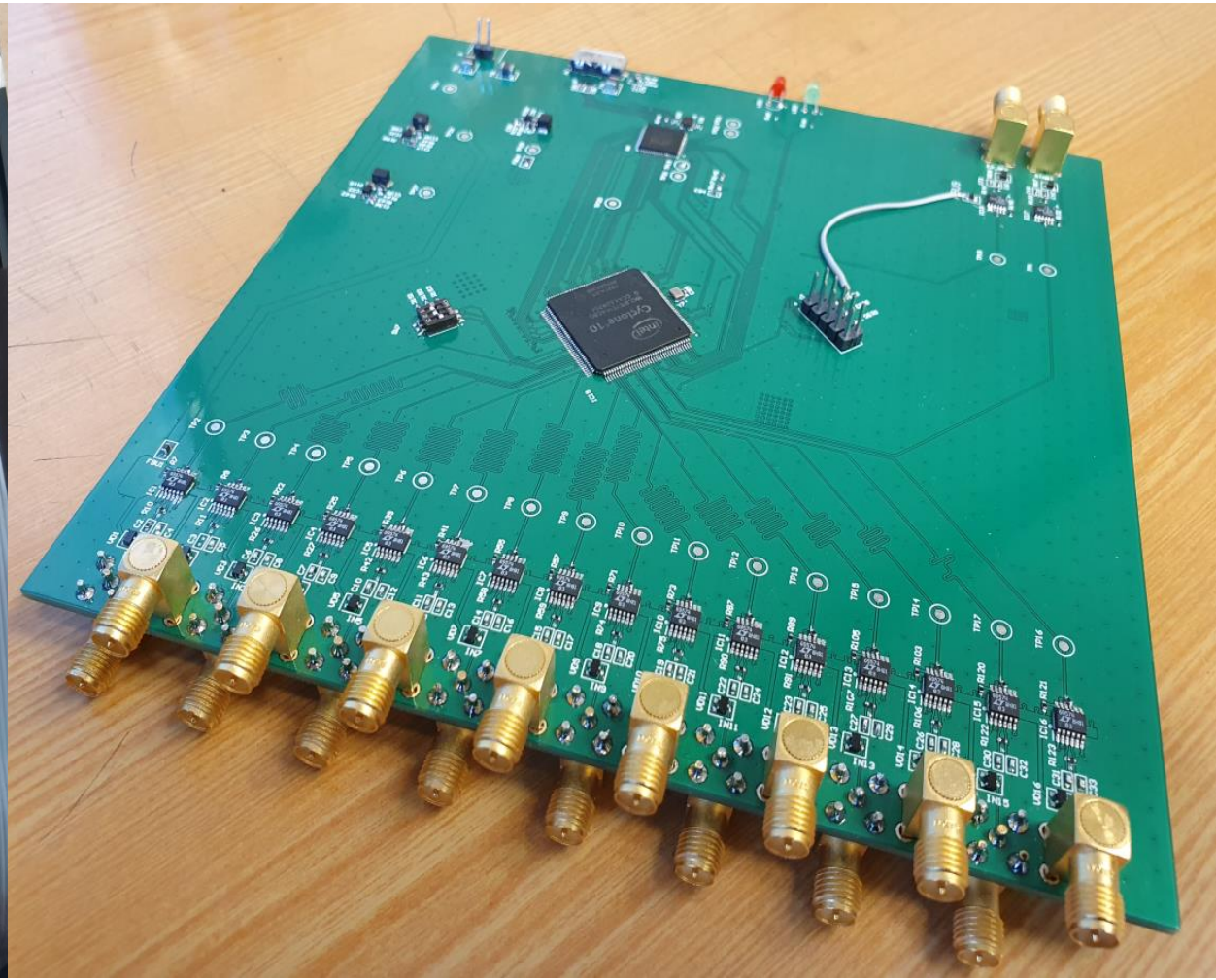
Meade Telescope; 45 degree mirror, monostatic configuration; elliptical scan mirror mount. Not showing: 355nm bandpass & Rayleigh Filter



# Photek Detector Array & Eventech Photon Counter: The Brain of the Lidar



16 Channel PMT-MCP Photek Detector Array



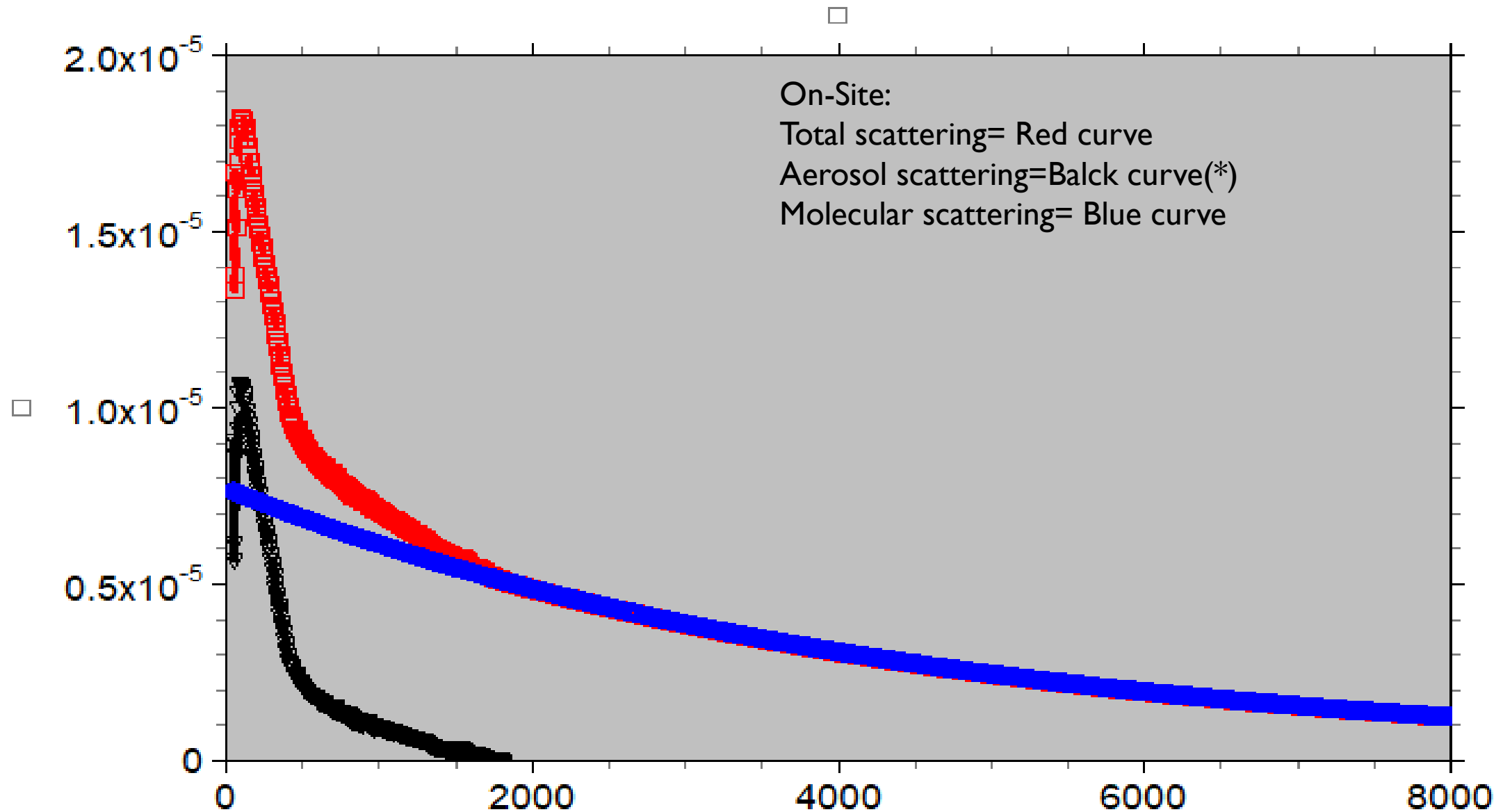
16 Channel Eventech Photon Counter Board

# DATA SET OUTPUT & PROCESSING STEPS

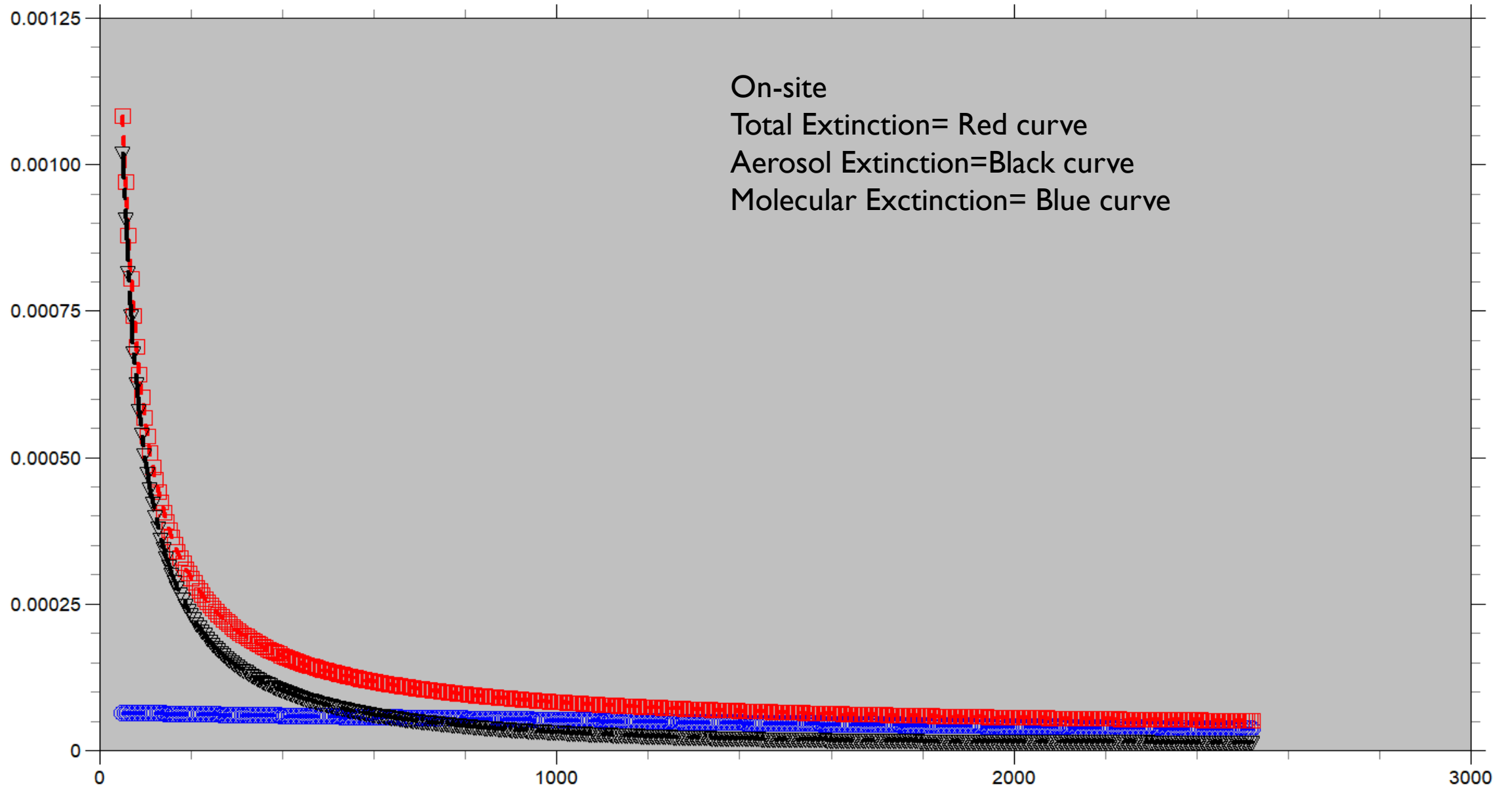
1. Multi-channel Detector output: atmospheric signal intensity profiles vs height (Point Clouds:  $x, t, S$  or  $x, \varphi, S$ )
2. Pre-processing of data: averaging,  $R^2$ , background subtraction, normalization & outputted as Excel file (TPF software)
3. Processing Wind of data: Cross-Correlation-Algorithm (CCA) of (Excel) data sets from subsequent scanned Images. CCA part of MATLAB DSP package



# SUPPORTING MEASUREMENTS: ATMOSPHERIC SCATTERING



# SUPPORTING MEASUREMENTS: ATMOSPHERIC EXTINCTION

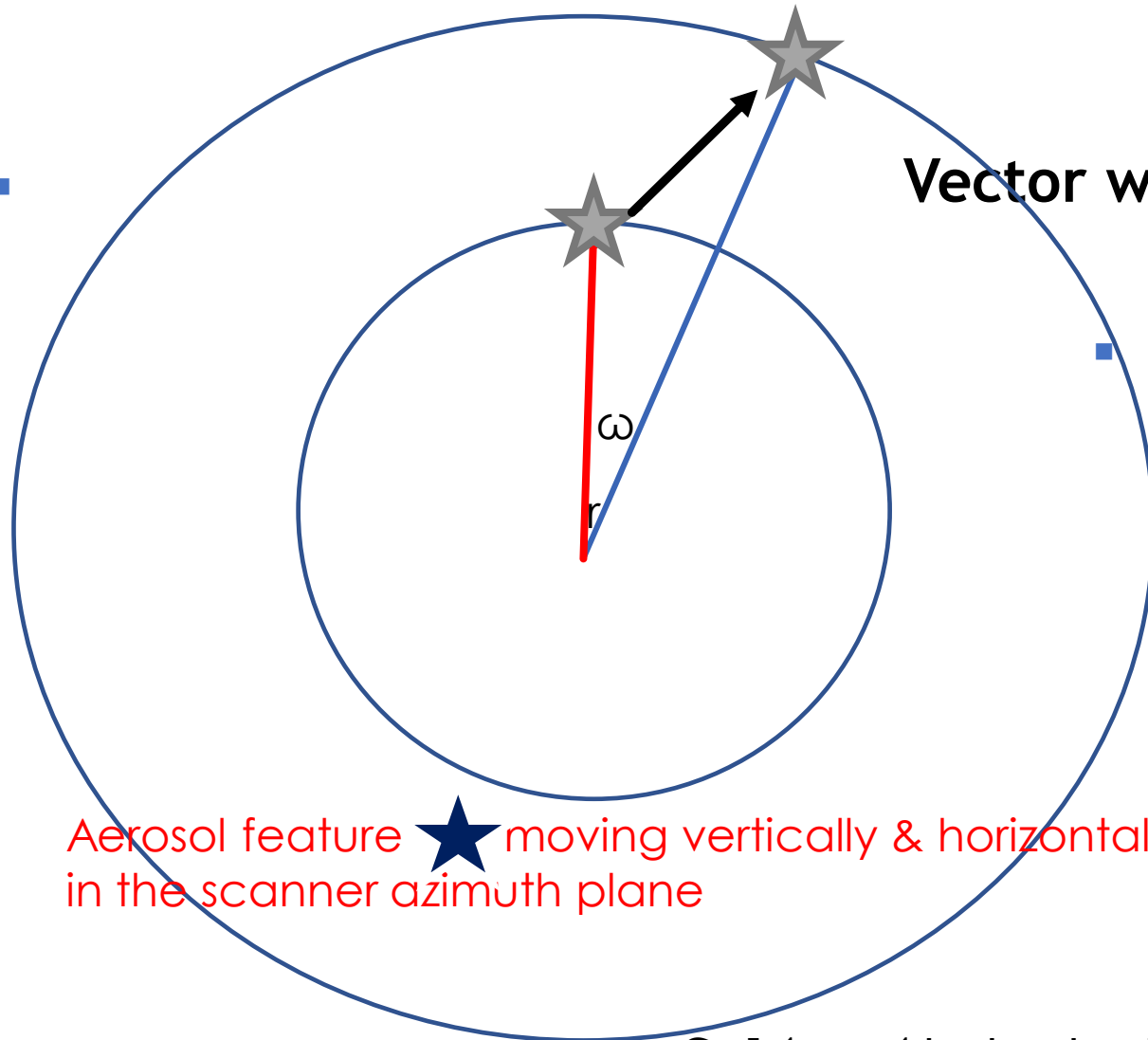




# Example of CWL data file

The Paradigm Factor Ltd																															
Date and 22092020-050434																															
Number ( 1																															
Number ( 4096																															
Sync Moc Single																															
Trigger P Leading Edge (Positive)																															
Integrati 1000																															
Bin Wid 66																															
Threshol 1.5																															
Fire Dela 0																															
Sync Dela 0																															
22.443	22.47	22.452	22.671	22.876	22.494	22.901	22.876	22.981	22.95	22.859	23.245	23.08	23.051	23.3	23.638	23.799	24.087	24.339	24.831	24.691	24.987	25.164	25.337	25.066	24.864	24.942	24.734	24.588	24.564	24.717	24.511
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32
Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel	Channel
2466	2503	2521	2543	2566	2577	2576	2557	2477	2495	2510	2537	2504	2484	2508	2431	2449	2492	2438	2431	2398	2375	2468	2430	2389	2184	2445	2514	2540	2528	2557	2438
2466	2503	2521	2543	2566	2577	2576	2557	2477	2495	2510	2537	2504	2484	2508	2431	2449	2492	2438	2431	2398	2375	2468	2430	2389	2184	2445	2514	2540	2528	2557	2438
2125	2122	2098	2092	2103	2051	2036	2056	2074	2089	2039	2100	2112	2102	2101	2115	2115	2109	2119	2076	2128	2089	2085	2119	2111	1915	2083	2132	2135	2136	2169	2140
2200	2208	2222	2180	2174	2177	2161	2112	2103	2048	2035	2089	2108	2141	2174	2094	2133	2110	2093	2131	2057	2081	2084	2130	2141	1925	2111	2212	2209	2213	2215	2245
2249	2282	2291	2322	2293	2284	2327	2281	2228	2171	2189	2247	2279	2297	2237	2180	2117	2163	2078	2039	2076	2192	2209	2221	2183	2036	2248	2184	2252	2237	2265	2263
2198	2190	2194	2206	2178	2178	2182	2228	2266	2277	2291	2312	2316	2288	2272	2329	2274	2239	2209	2201	2235	2212	2207	2240	2216	2083	2205	2256	2286	2278	2320	2233
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1723	1659	1647	1660	1582	1553	1531	1585	1556	1630	1652	1719	1805	1838	1798	1884	1992	2002	2127	2052	1943	1671	1748	1875	1779	1631	1862	1870	1828	1822	1799	1735
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622	612	629	637	635	600	614	569	603	566	570	594	615	664	746	734	732	694	693	683	650	650	645	652	609	543	631	665	683	656	661	690
540	526	547	549	498	509	533	498	521	500	515	508	506	579	621	622	623	605	653	547	581	520	573	572	521	475	577	574	568	612	586	583
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93	106	125	110	116	124	117	95	100	102	105	108	126	141	130	141	142	114	114	110	129	111	128	117	116	98	107	112	115	135	104	120

# Pictorial view of wind calculation (Polar)



Vector wind :  $U = (R +/- \textcircled{dr}) * \sin(360 +/- \textcircled{\omega}) / (T +/- \textcircled{dt})$

Aerosol feature ★ moving vertically & horizontally in the scanner azimuth plane

0.0655	-0.5478	-0.5947	-0.6683	-0.6225	-0.6186	-0.6118	-0.7753	-0.2270
-0.1214	-0.5272	-0.6850	-0.6222	-0.6542	-0.6666	-0.6861	-0.5482	-0.1604
0.0312	-0.0769	0.3308	0.5059	0.3948	-0.4927	0.3931	-0.0237	0.0742
0.0334	-0.0749	0.0337	0.1667	-0.6462	-0.2703	-0.1159	-0.0469	0.0681
0.0309	-0.0228	0.2143	0.0564	0.0731	0.3814	-0.0807	0.0453	0.1068
0.0435	-0.0027	0.8473	0.0106	0.6889	0.5994	<u>0.8003</u>	0.0225	0.0976
0.0492	-0.0668	0.3444	0.5648	0.6754	0.5418	0.4620	0.0031	0.0693
-0.0305	0.3914	0.6053	0.6700	0.6375	0.6403	0.6286	0.6227	0.2646
0.2128	0.5466	0.6758	0.6874	0.6764	0.6863	0.6811	0.6167	0.3239

Template A= 3x3  
Image B= 7x7

Correlation Matrix  
Dimensions : 3 + 7 - 1

$C_{ij}$  [-4 to +4 both indices]  
i: scan in range, j: scan in azimuth/time



# EXAMPLE OF IMAGE(B: 5X5) & TEMPLATE(A: 3X3) MATRICES FROM CONTIGUOUS SCANS TO MATLAB

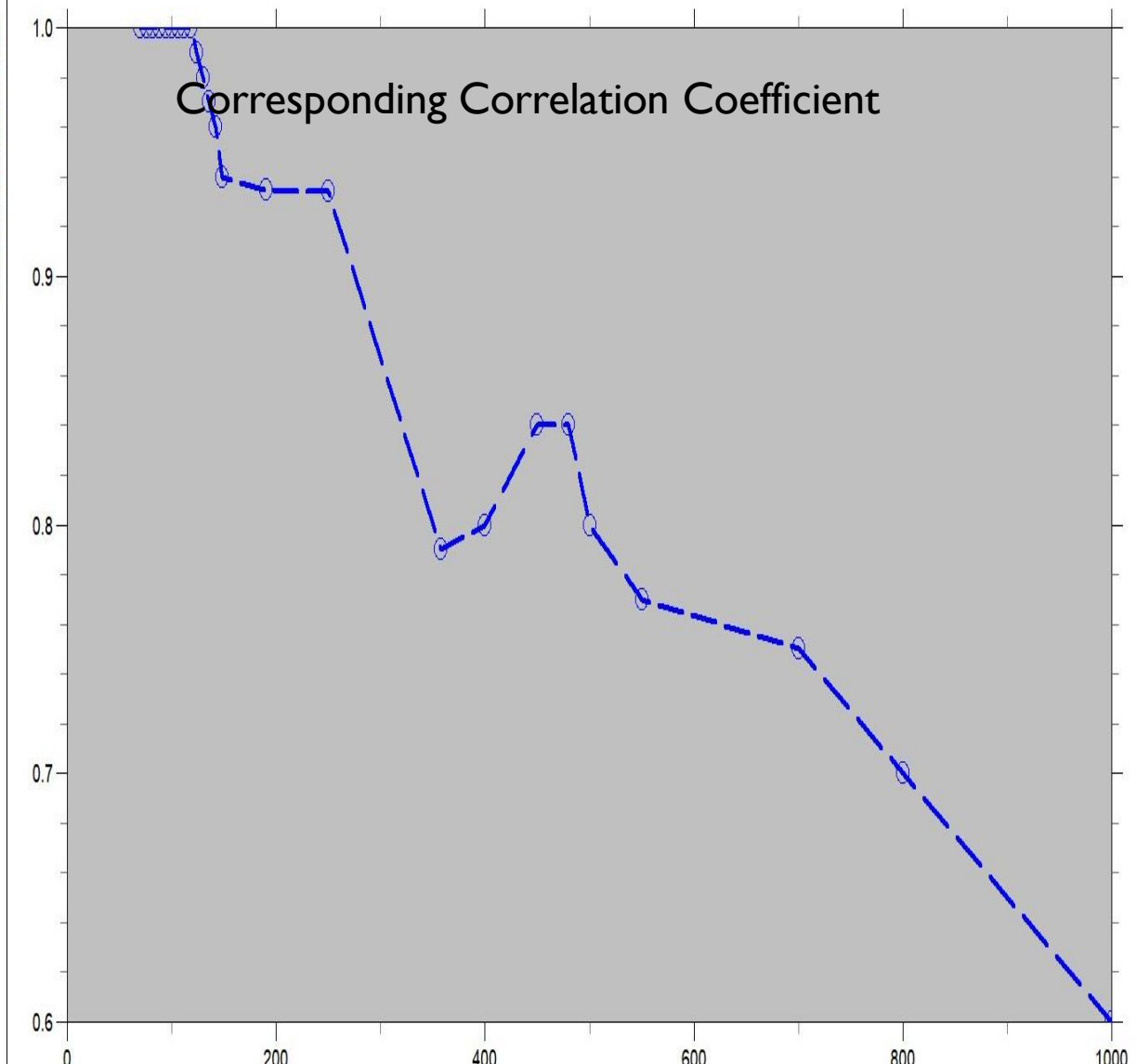
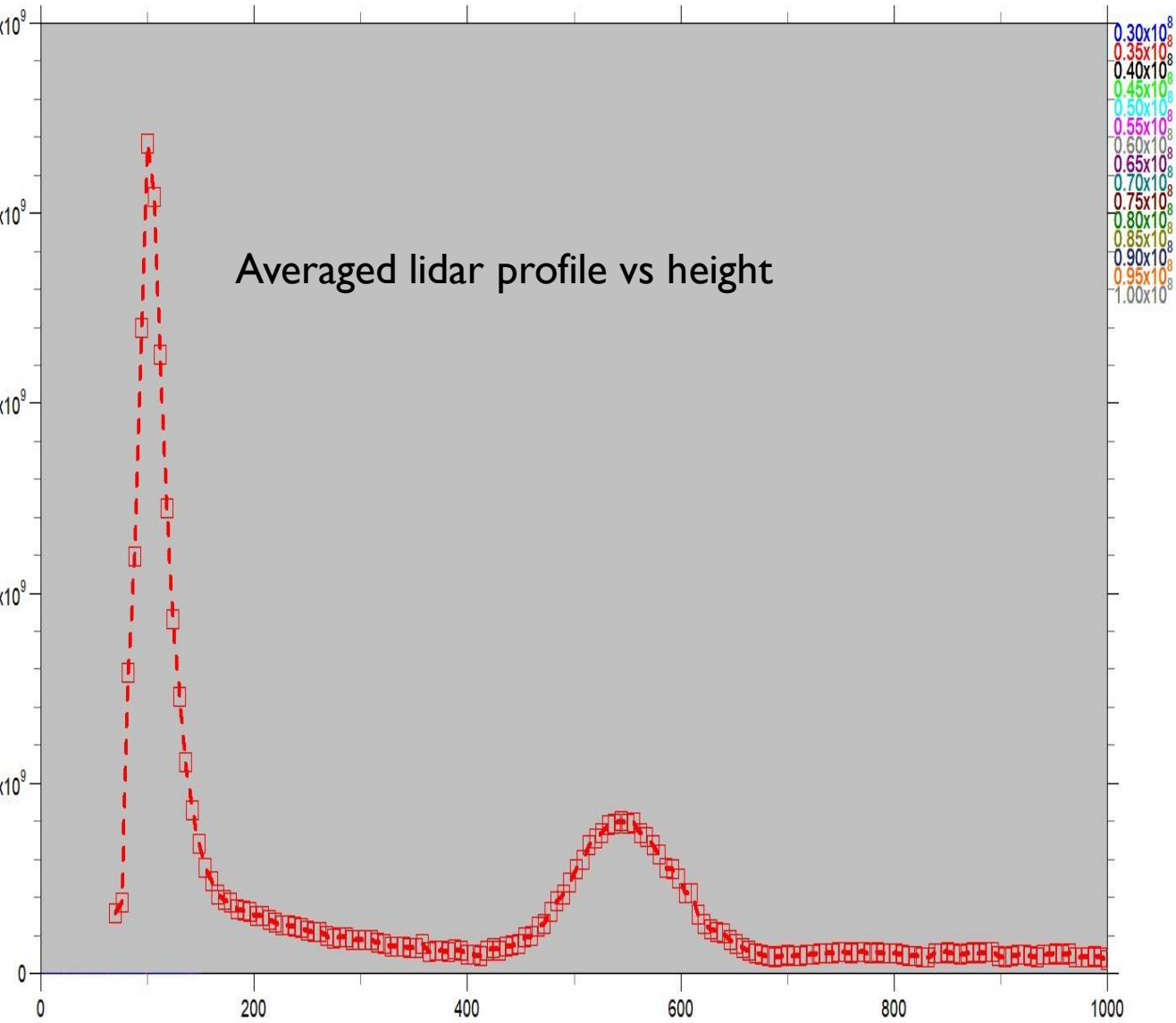
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8973	8971	8789	5061	7001	8736	8402	9065
8336	8822	8462	4865	6566	7913	8041	8220
7311	8117	7850	4577	6188	7259	7168	7469
6632	7053	6987	4116	5395	6399	6117	6452
5759	6388	6215	3616	4620	5422	5184	5648
4842	5498	5475	3183	4064	4714	4377	4856
4504	4999	4921	2837	3670	4299	3720	4217
3753	4555	4571	2634	3267	3792	3384	3723
3538	4082	4112	2379	3011	3399	3037	3411
3250	3547	3631	2159	2699	3212	2681	3225
2990	3390	3417	2128	2486	2818	2634	2877
2769	3165	3225	1984	2358	2627	2369	2589

**A**

8655	9047	8927	3740	8503	8945	8416	8692	8717	8876	7481
9043	9096	9111	3794	8082	8973	8420	8771	9240	8857	7489
8372	8752	8673	3752	7581	8351	7985	8203	8702	8704	7140
7785	8279	7912	3590	7002	7517	7196	7344	7970	7956	6635
6820	7305	7001	3111	5927	6552	6094	6587	7170	7149	5738
5759	6441	6302	2784	5294	5708	5242	5617	6237	6409	5044
5154	5710	5614	2424	4545	4887	4531	4962	5500	5603	4484
4425	5097	4935	2165	4116	4386	3954	4296	4988	5091	4058
4061	4536	4359	2001	3621	3703	3407	3793	4329	4494	3517
3655	4111	3917	1795	3450	3463	2983	3433	3869	3983	3238
3320	3645	3691	1713	3084	3103	2787	3004	3455	3658	2985
3014	3421	3297	1652	2863	2835	2586	2958	3266	3462	2789
2828	3168	3168	1588	2620	2615	2419	2648	2975	3239	2540

**B**

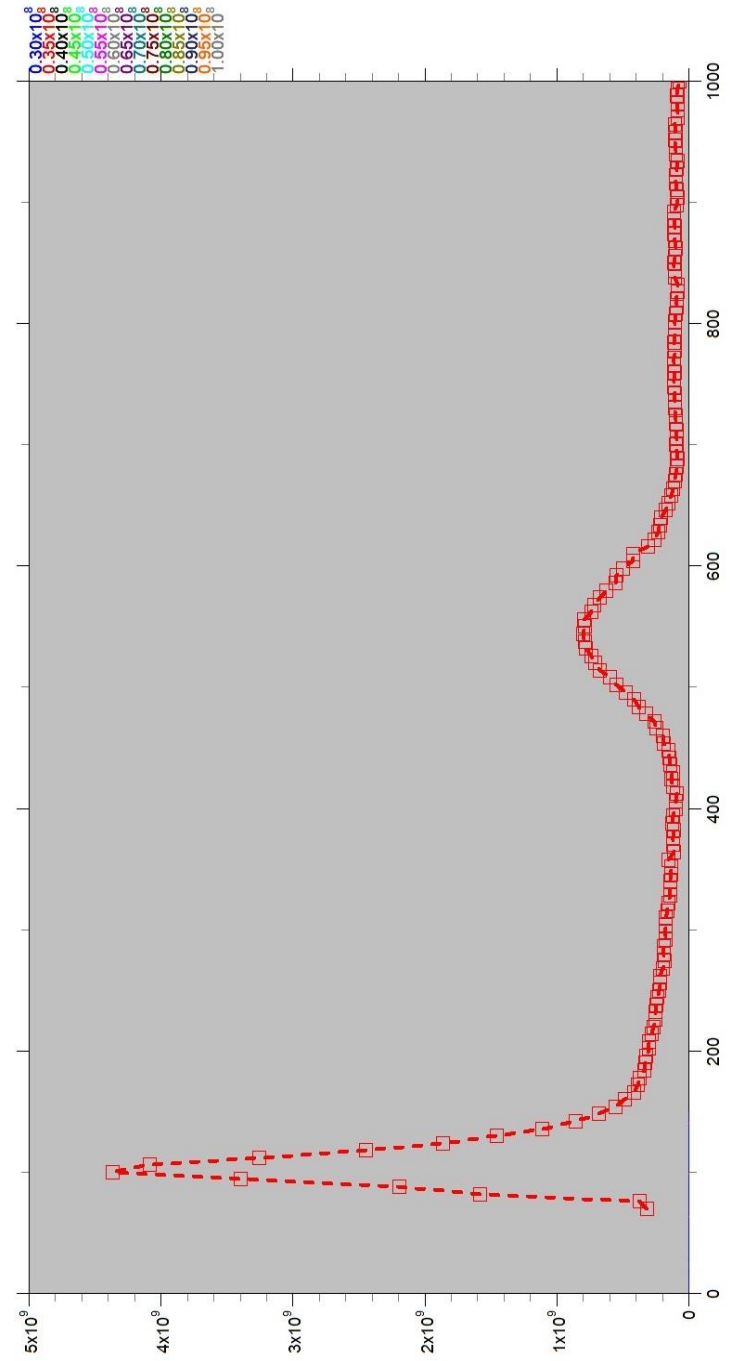
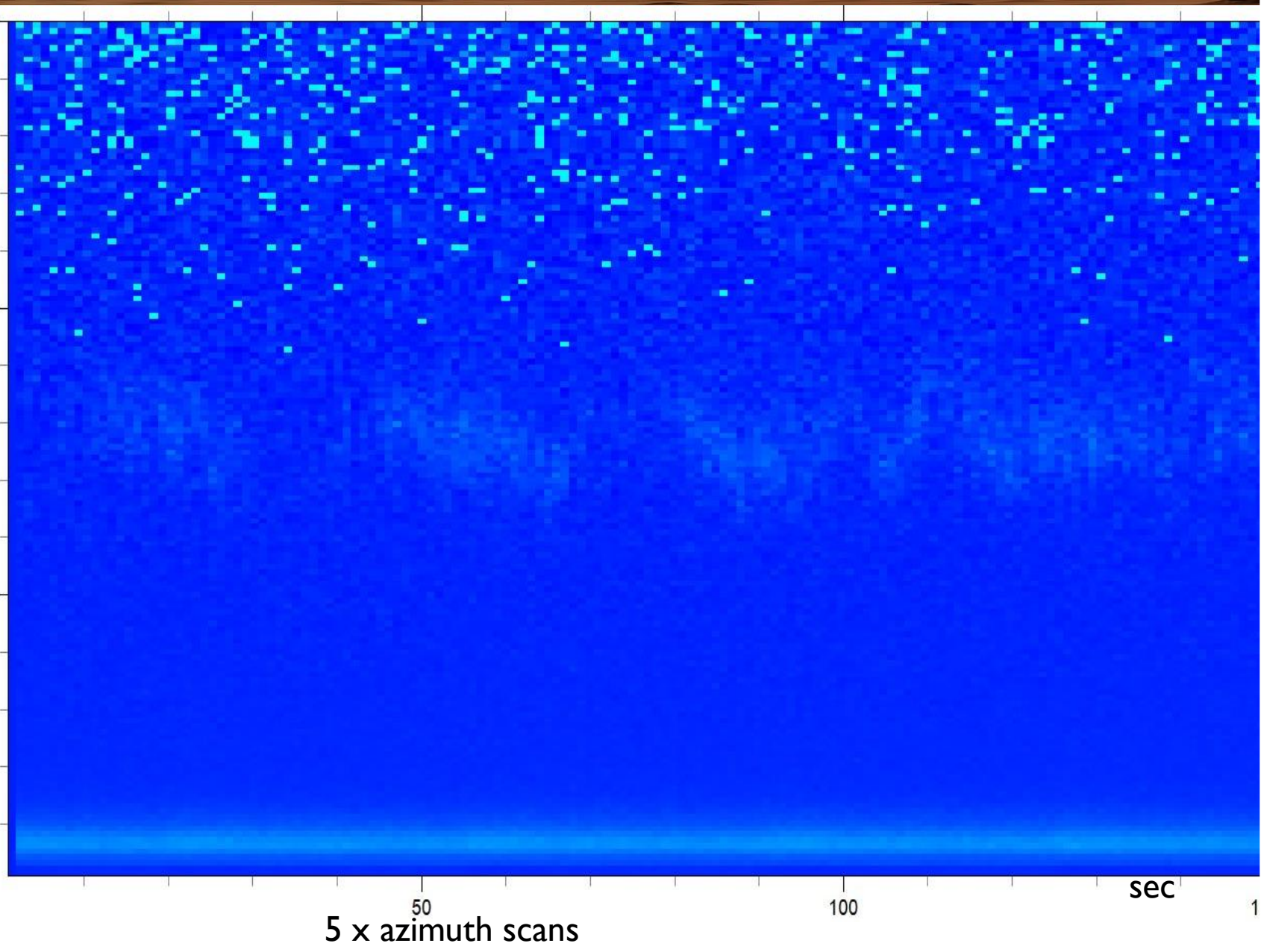
# Examples of Winds: case 1



Show case 1: July 2020; location: West Sussex; country, low aerosol load, quiet & clear summer night

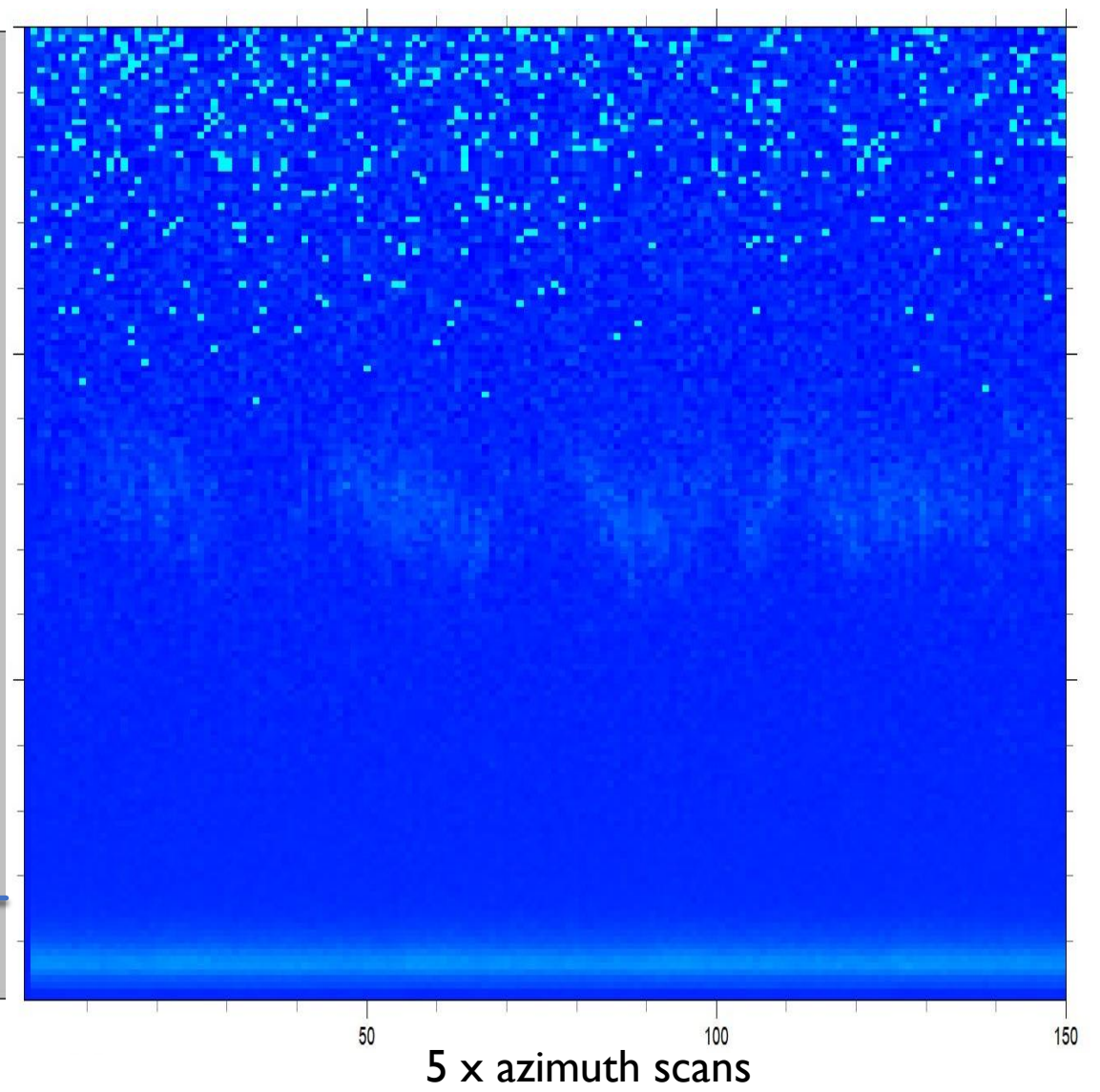
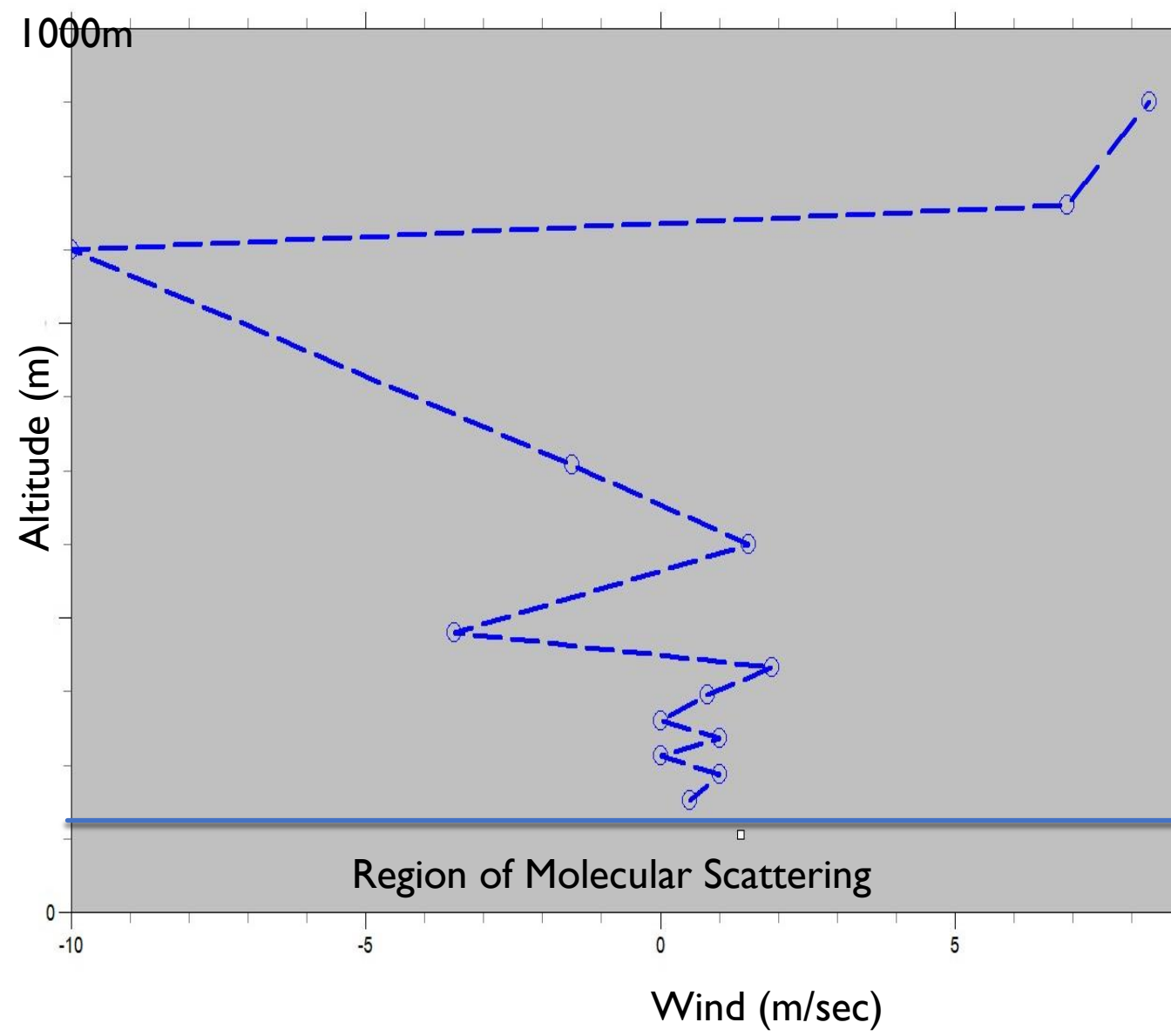


# Winds: case 1



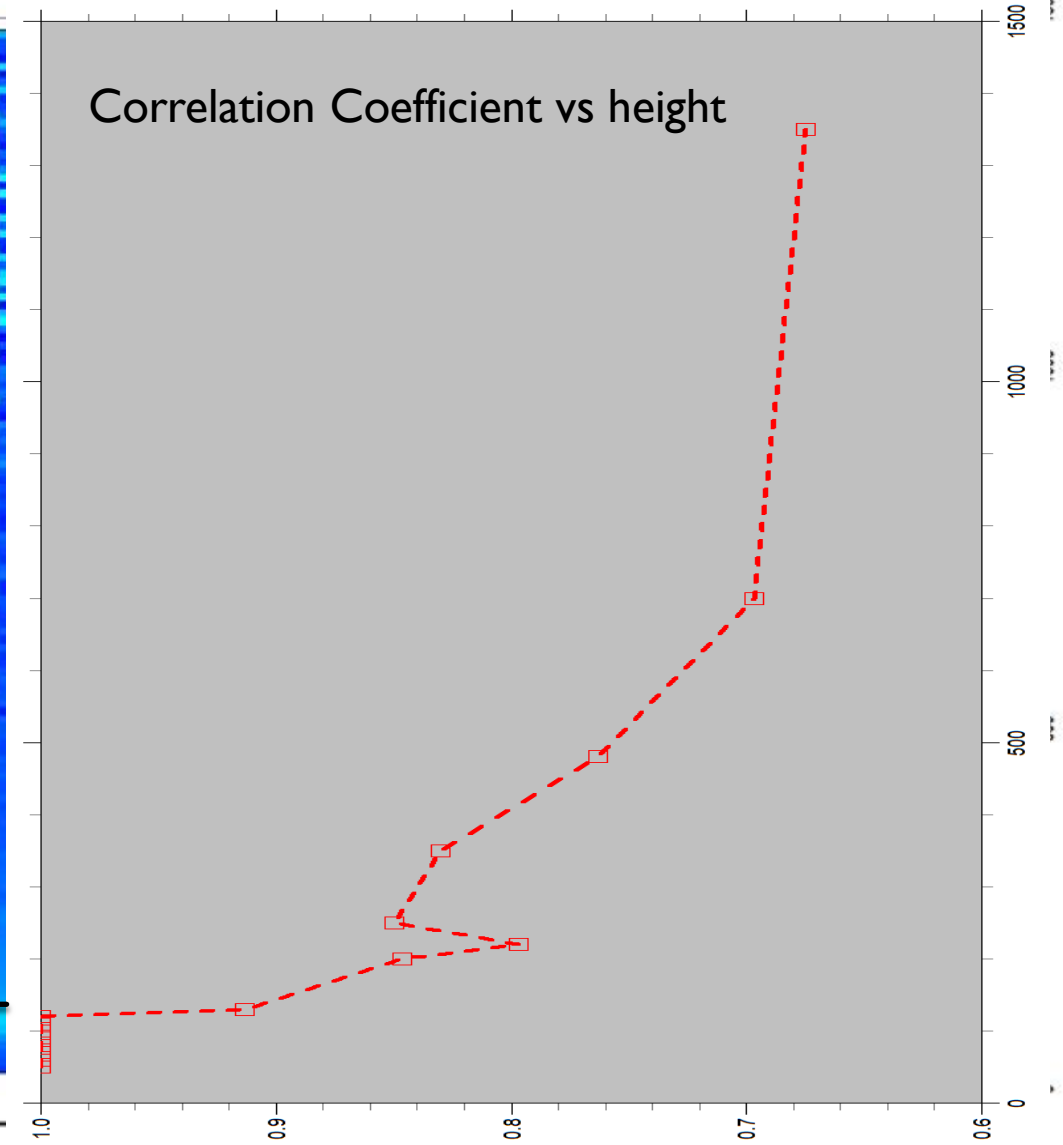
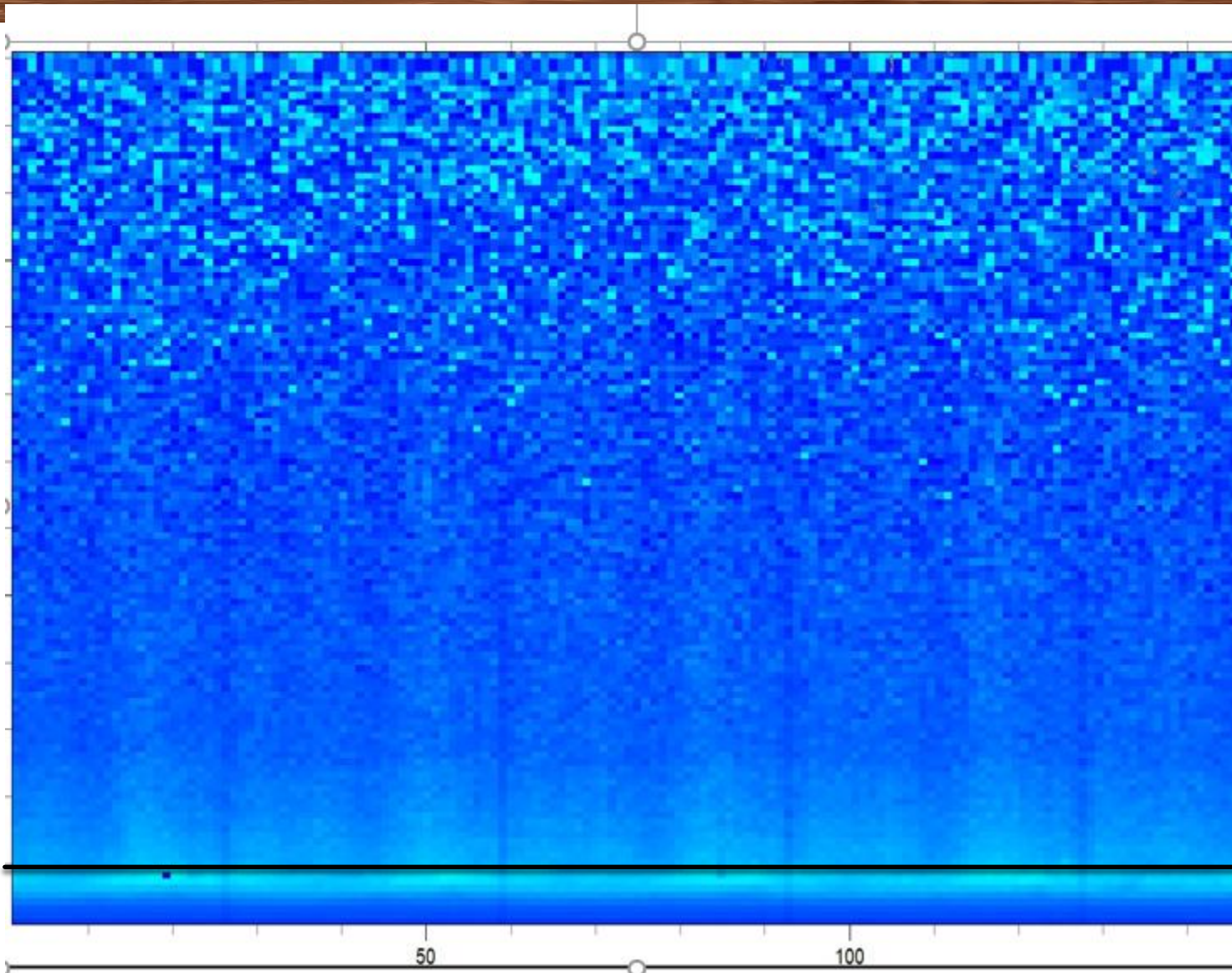
8  
0.30x10<sup>8</sup>  
0.35x10<sup>8</sup>  
0.40x10<sup>8</sup>  
0.45x10<sup>8</sup>  
0.50x10<sup>8</sup>  
0.55x10<sup>8</sup>  
0.60x10<sup>8</sup>  
0.65x10<sup>8</sup>  
0.70x10<sup>8</sup>  
0.75x10<sup>8</sup>  
0.80x10<sup>8</sup>  
0.85x10<sup>8</sup>  
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0.95x10<sup>8</sup>  
1.00x10<sup>8</sup>

# Winds: case 1



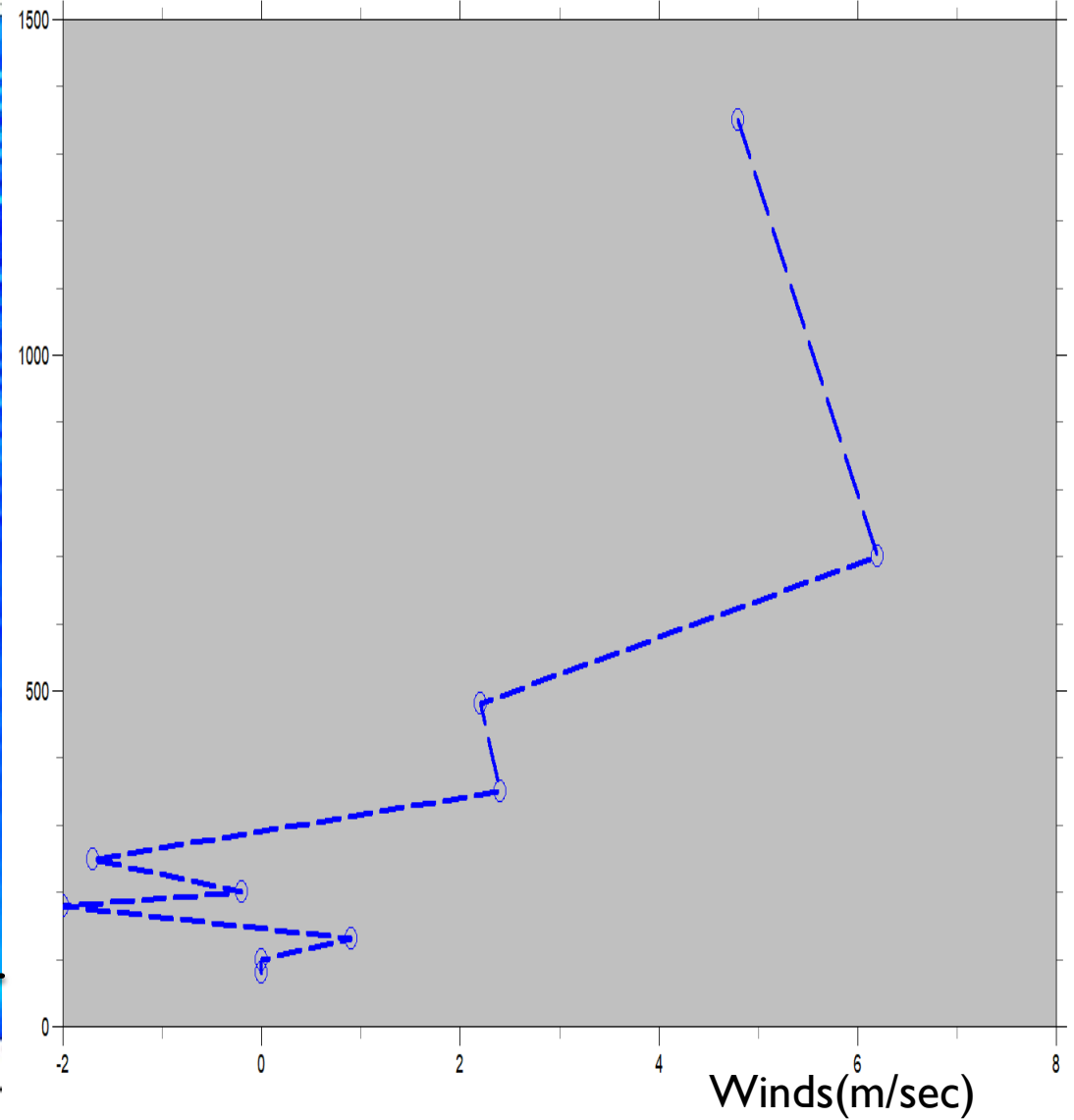
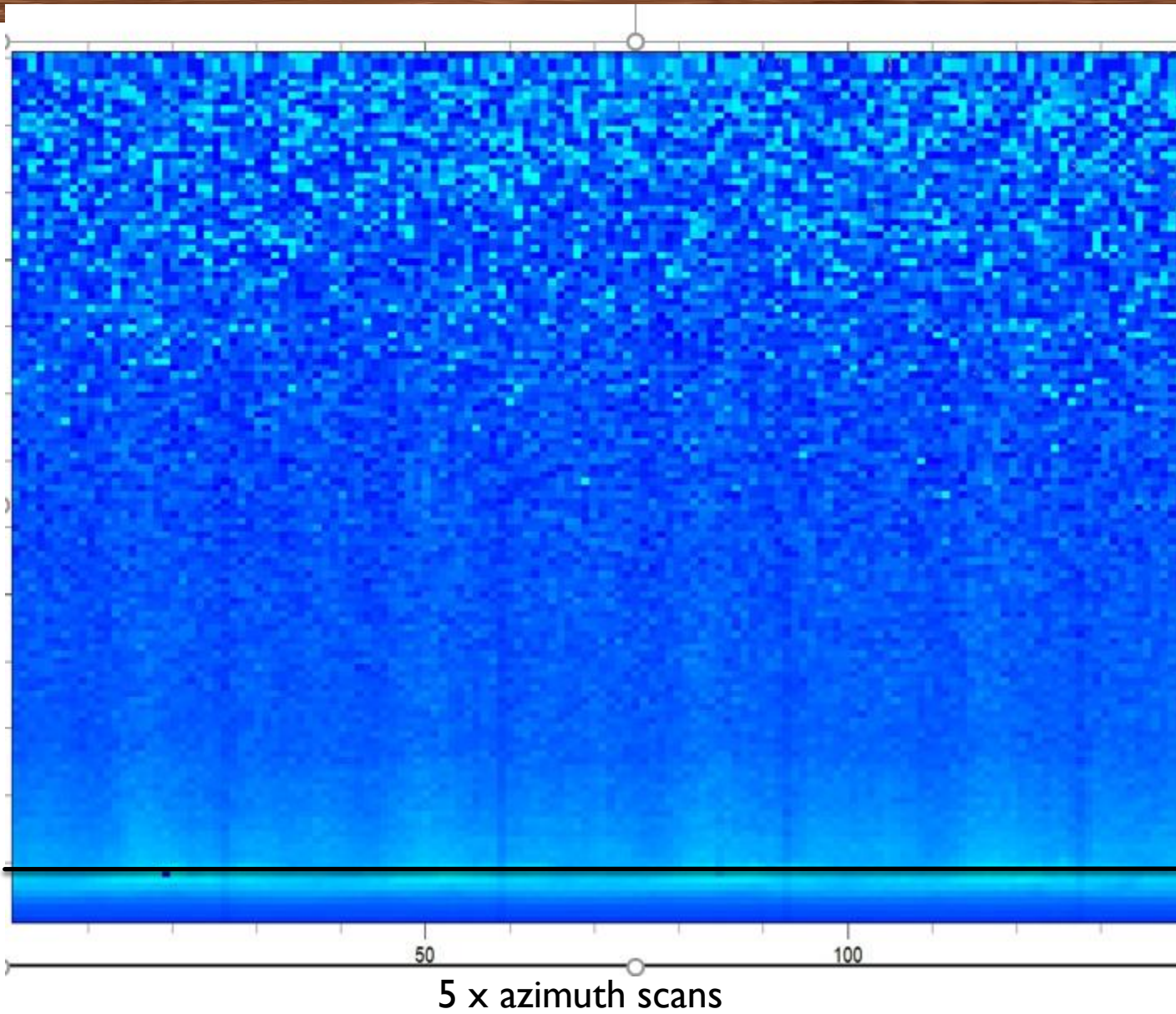


# Winds: case 2



Show case2: September;2020 location:West Sussex; country, low aerosol load, quiet & clear summer night

# Winds: case 2





# Conclusions & Outlook

- The CWL lidar technique with DSP processing has demonstrated that it can provide atmospheric winds, offering significant system simplification in terms of H/W, S/W & Processing.
- The New Instrument Concept is multifunctional & can be applied to Altimetry & Imaging (already demonstrated)
- Tx complexity traded & replaced by Processing & on-board Computer Power
- Downscaling in Swap Technology possible & feasible for applications in Planetary & Earth Sciences
- A “PIC” down-scaled model under investigation with ESA
- Combination with Passive sensors (cameras) & Sensor fusions opens up the use in GNC & Landing for Planetary research (Mars, Moon, etc): initial steps being investigated with European Industrial Consortium

# The CWL Team & Acknowledgment

The work presented has been partly supported by the European Space Agency under PECS Framework Program Contract No. 4000130586/20/NL/SC, started May 2020

The Project Team comprises:

- ❖ E. Armandillo, Eventech Advisor: CWL overall system engineer & Wind Processing
- ❖ D. Rees, The Paradigm Factor (UK): CWL Lidar lead engineer, Assembly & Testing
- ❖ V. Kurtenoks & I. Pulkstenis (Eventech) : 16 Channel Timer & Single Photon Counter
- ❖ Photek Limited (UK): PMT Array Supplier

**THANK YOU FOR YOUR ATTENTION !!!**