



Physics Scotland



CMSIN NSTP3-PF-031

Single Pixel Camera for Remote Sensing

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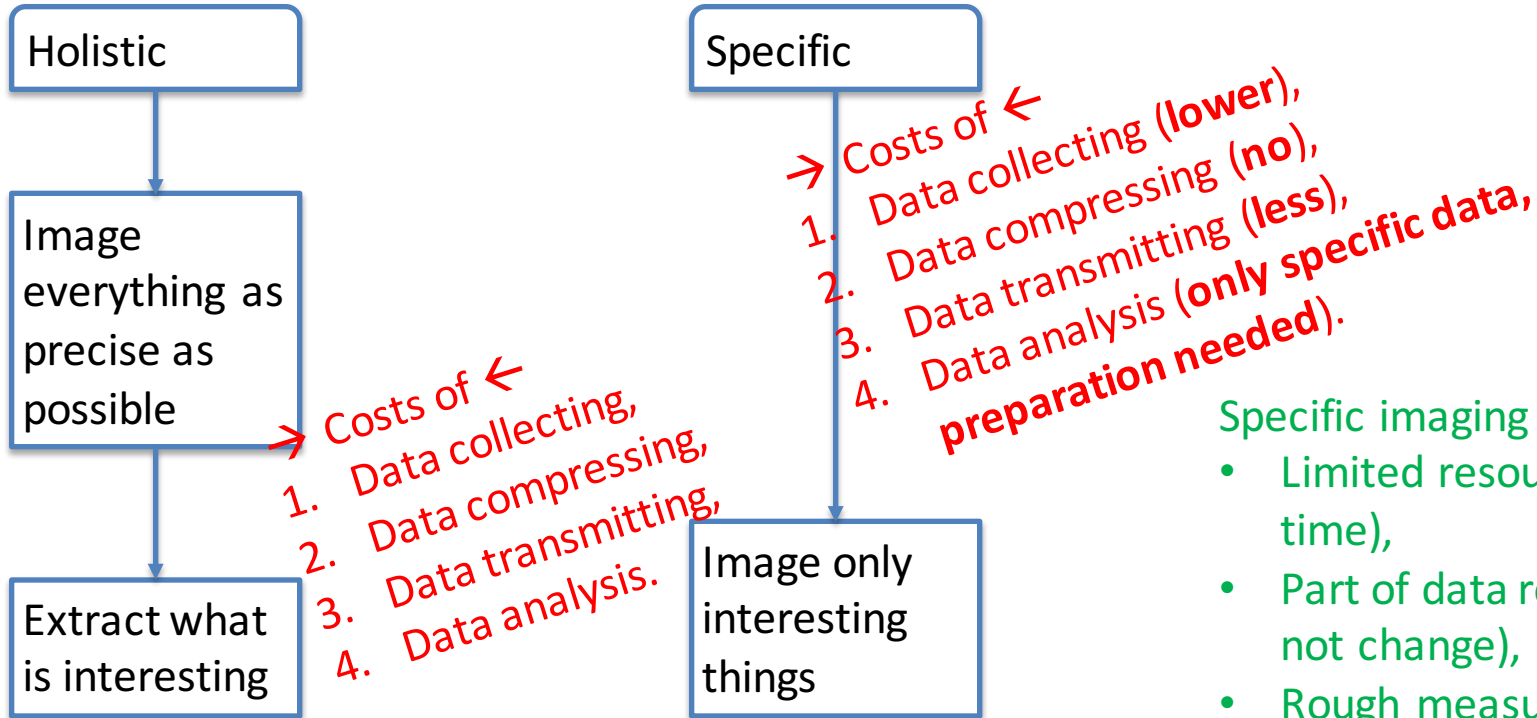
NSTP3 Pathfinder project
(NSTP3-PF-031)

Compact Multi-Spectral
Imager for Nano-satellites

Feasibility Study


All comments and
suggestions on possible
applications are welcome.

Main Imaging Paradigms




- Specific imaging is useful when
- Limited resources (power or time),
 - Part of data redundant (do not change),
 - Rough measurement followed by more holistic.

Cube Sats



CubeSats NASA's CubeSat Programs provide opportunities for small satellite systems to fly as auxiliary payloads on planned missions. These spacecraft (each about 10 cm on a side) facilitate science, exploration, and technology development, and advance educational goals in partnership with universities, industry, and NASA. JPL's Earth exploration CubeSats are designed to support Earth science technology and research.



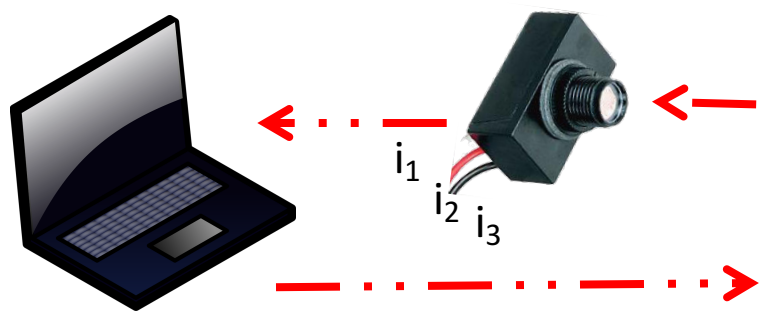
MCUBED/COVE-2 • IPEX • GRIFEX • RACE

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features of Cube Sats:

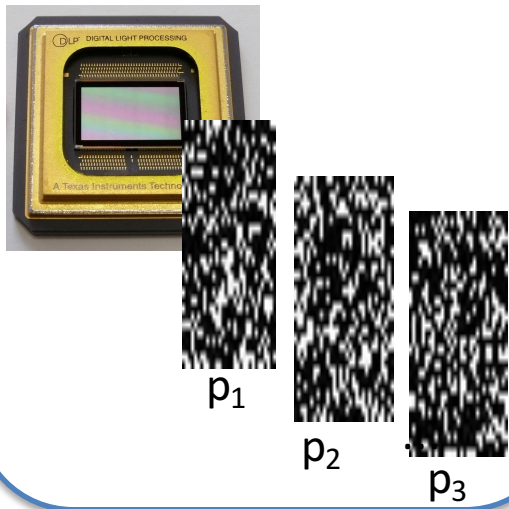
- Small,
- Cheap,
- Flexible,
- Short-life,
- Limited power,
- Off-the-shelf components.

Single-pixel camera



- in non-typical wavelength ranges
- limited space
- Simple electronics
- resolution dependent on masks
- Adaptive measurements
- Computer vision
- **Compressive sensing**

Digital micromirror device

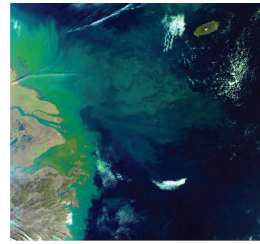
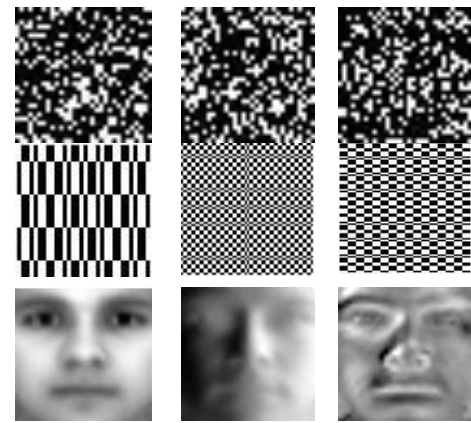


Optical processor

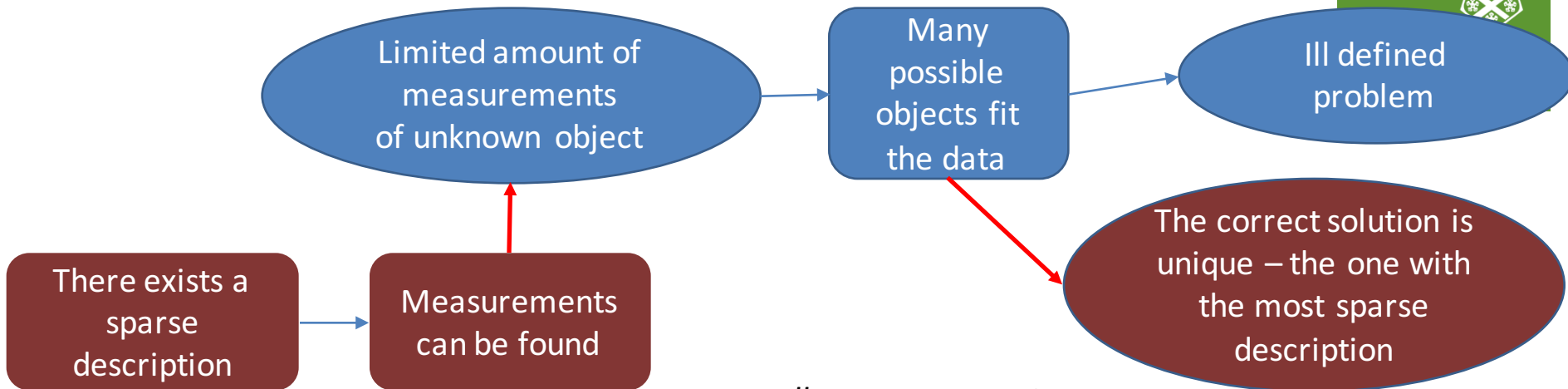
Random

Hadamard

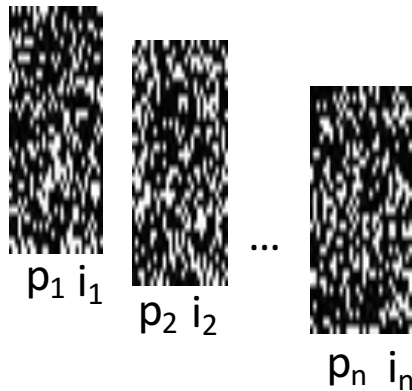
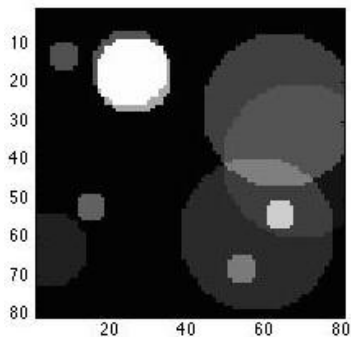
More specific masks



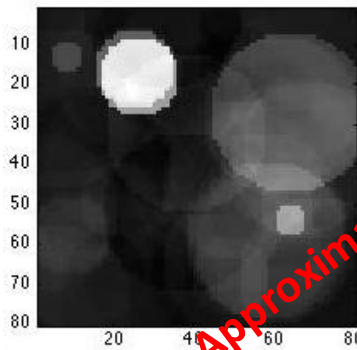
Compressive sensing



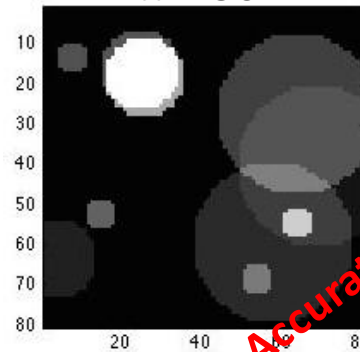
pixels = 6400



measurements
 $n=130$

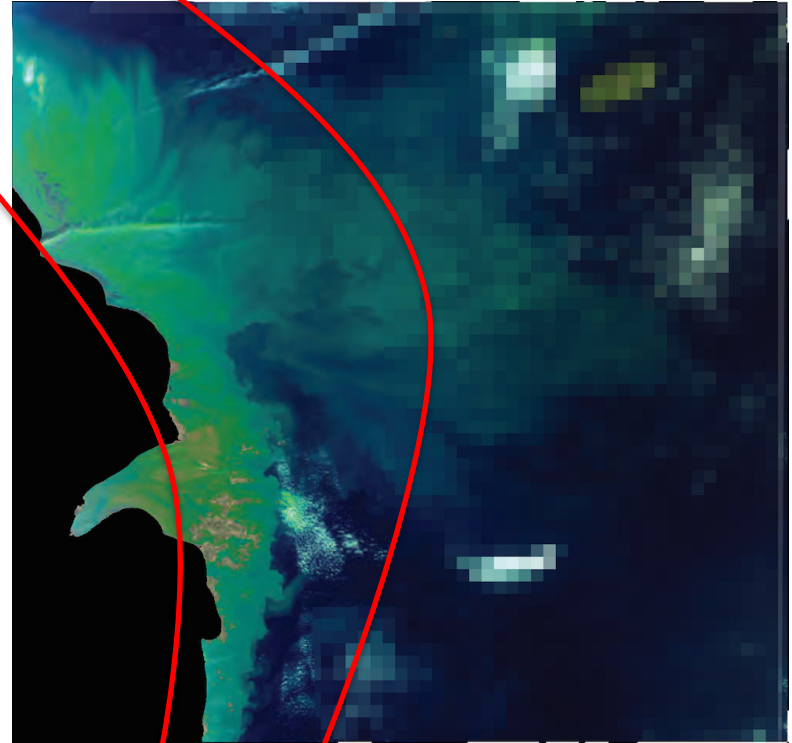
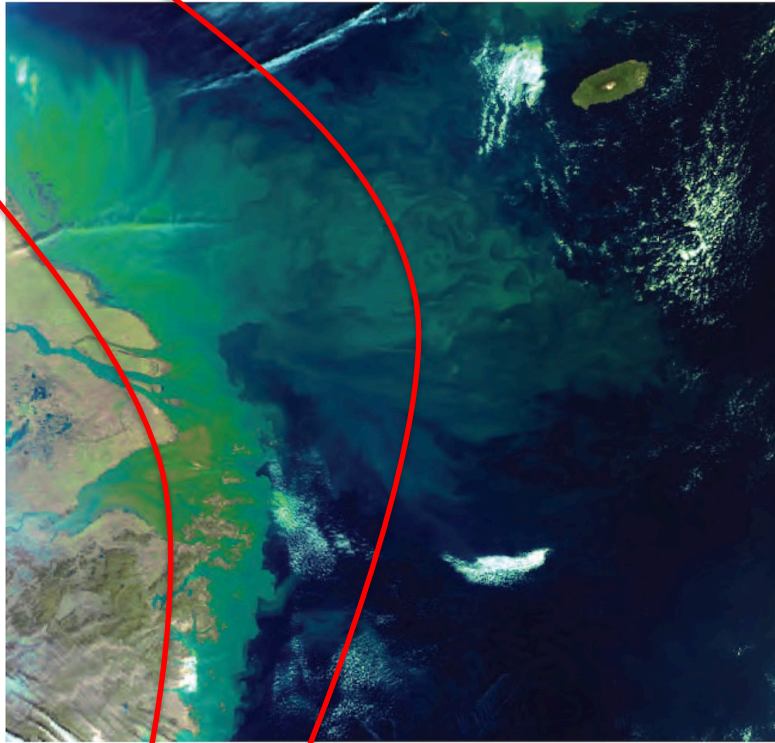


$n=150$

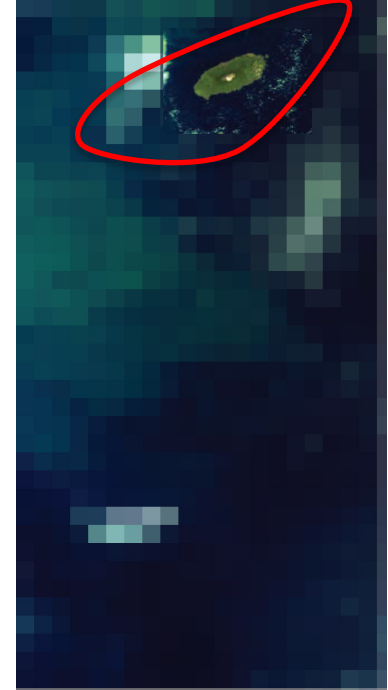
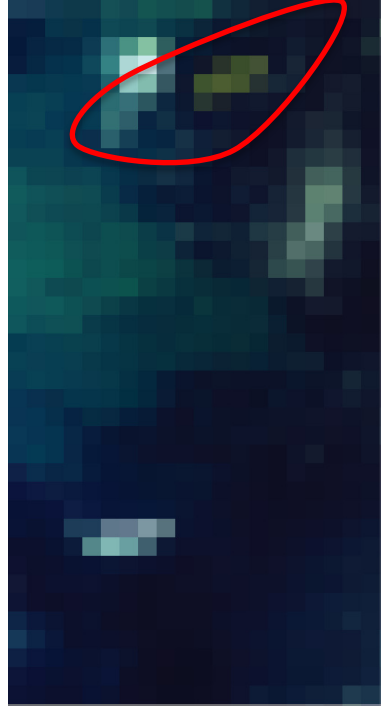
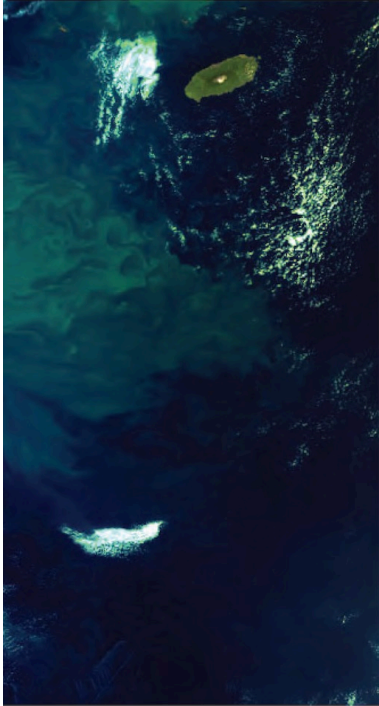


2.5%
of
pixels

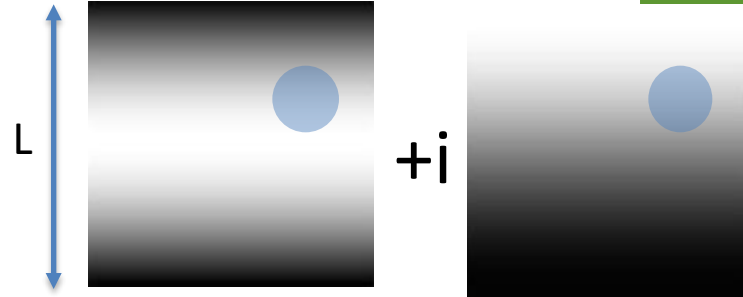
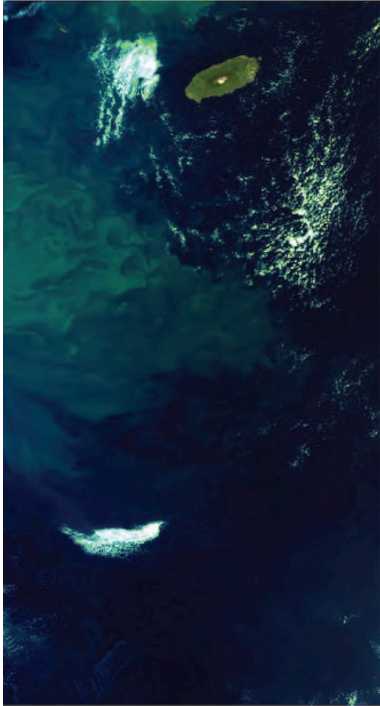
Variation of resolution, data reduction



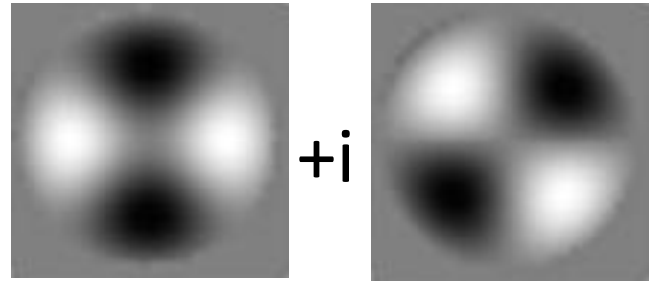
Resolution improvement locally, if needed



Fast localisation of position and orientation with measurement of 6 intensities



$$F_1[g(x-d)] = F_1[g(x)]e^{i\pi d/L}$$



$$F_2[g(r, \phi - \theta)] = F_2[g(r, \phi)]e^{2\pi i \theta}$$

Summary and challenges

What we can offer?

Why the single-pixel camera for nano-sats?

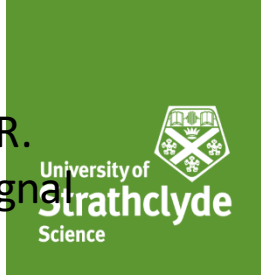
- Cheap, simple, efficient (off-the-shelf components)
- Specific imaging
- Low transmission rate
- Programmable (machine vision techniques on board including compressive sensing)
- Works well in constellations
- Multispectral (vis, mid IR)

Challenges:

- Moving platforms, acquisition speed
- Case dependent software, real time signal processing
- SNR of current implementations

Possible solutions:

- See Fowler, compressive pushbroom and whiskbroom sensing for hyperspectral remote-sensing imaging, ICIP, 2014 IEEE.
- Machine learning, preprocessing, efficient algorithms being developed,
- Alternative architectures being investigated.



Single-pix. cam

- M. Duarte, M. Davenport, D. Takhar, J. Laska, T. Sun, K. Kelly, and R. Baraniuk, “Single-pixel imaging via compressive sampling,” IEEE Signal Process. Mag., (2008).

Compressive sensing

- E. Candes and T. Tao, “Decoding by linear programming,” IEEE Trans. Inf. Theory, (2005).
- D. Donoho, “Compressed sensing,” IEEE Trans. Inf. Theory, (2006).
- M. Duarte, M. Davenport, D. Takhar, J. Laska, T. Sun, K. Kelly, and R. Baraniuk, “Single-pixel imaging via compressive sampling,” IEEE Signal Process. Mag., (2008).

Single-Pixel Remote Sensing

- J. Ma, “Single-Pixel Remote Sensing” IEEE Geoscience and remote sensing Lett. (2009).
- J. E. Fowler, “Compressive pushbroom and whiskbroom sensing for hyperspectral remote-sensing imaging”, ICIPI IEEE (2014).