# Software Defined Multifunction LIDAR



QINETIQ

### Introduction: QinetiQ















## Introduction: Software Defined Multifunction LIDAR (SDML)

#### What is LIDAR?

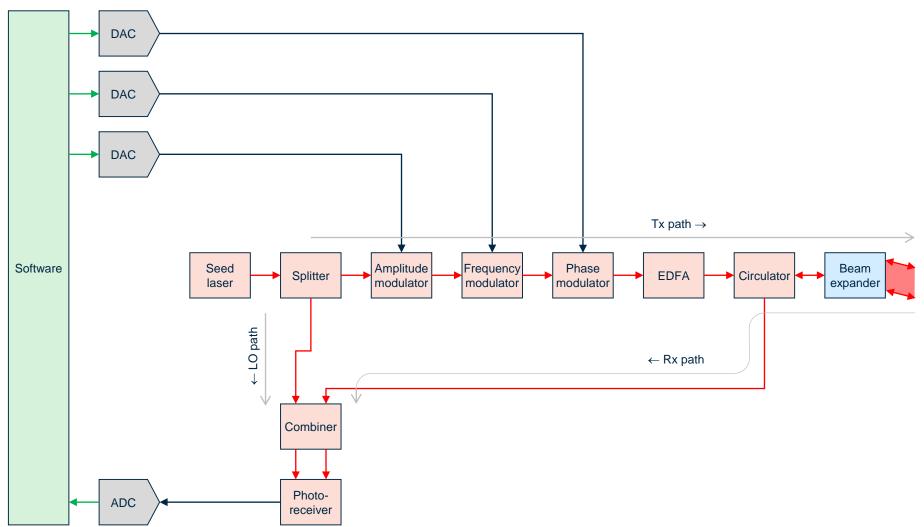
- Like radar but using light.
- Many different types:
  - Range finding, 3D imaging.
  - Velocimetry, vibrometry, anemometry.
  - Optical comms, retro-comms.
- Fundamentally, what discriminates them?:
  - The mod-demod scheme.
  - One or two schemes are 'hard-wired' into conventional LIDAR systems.

#### What is SDML?

- Mod-demod abstracted into software.
- Switch between sensing modalities at run time.
- Allows many modes in a single payload.



## Introduction: Software Defined Multifunction LIDAR (SDML)



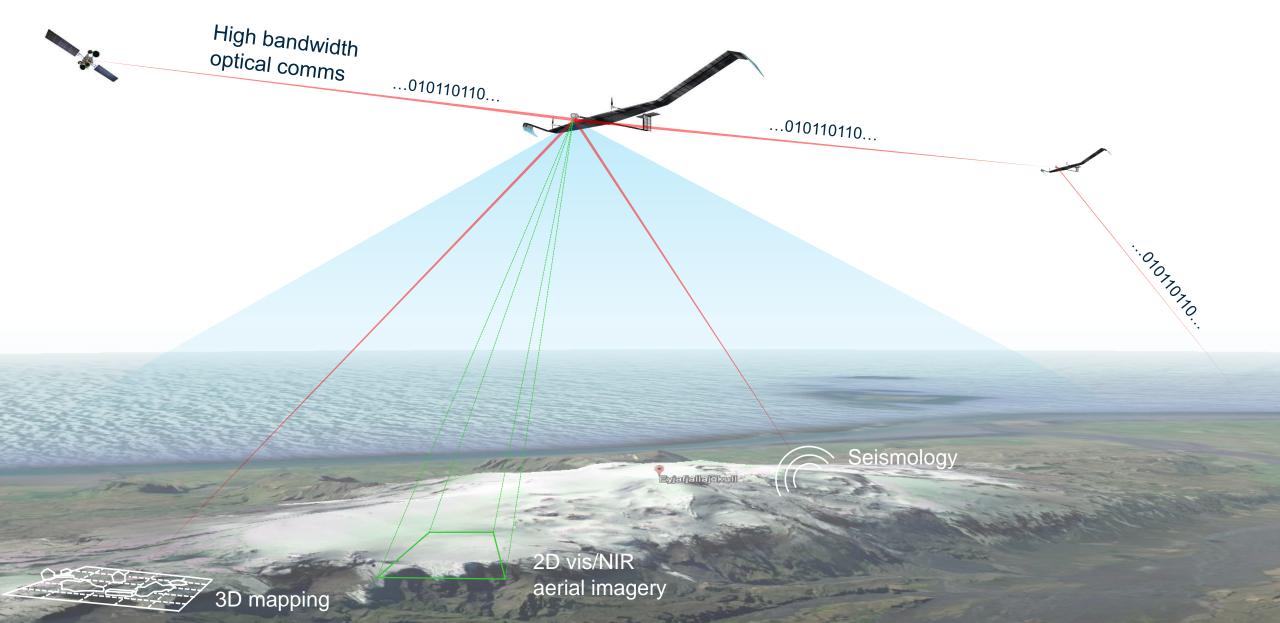


# SDML: Earth Observation Capability

Sensing Mode	Application Examples
3D imaging/mapping.	Mapping, planning, biomass monitoring, precision agriculture, disaster/damage assessment.
2D vis/NIR imaging	Conventional aerial imagery, NDVI imagery.
Vibrometry.	Stand-off seismology.
High bandwidth covert optical comms.	GBit+ covert, secure, bidirectional comms.
Retro-comms.	Comms 'tags' for unattended ground sensors.



# SDML: Earth Observation Capability





#### SDML for HAPS





2 x flight capable SDML payloads



Demo: covert, secure high bandwidth optical communications

HAPS payload design advice and environmental testing.

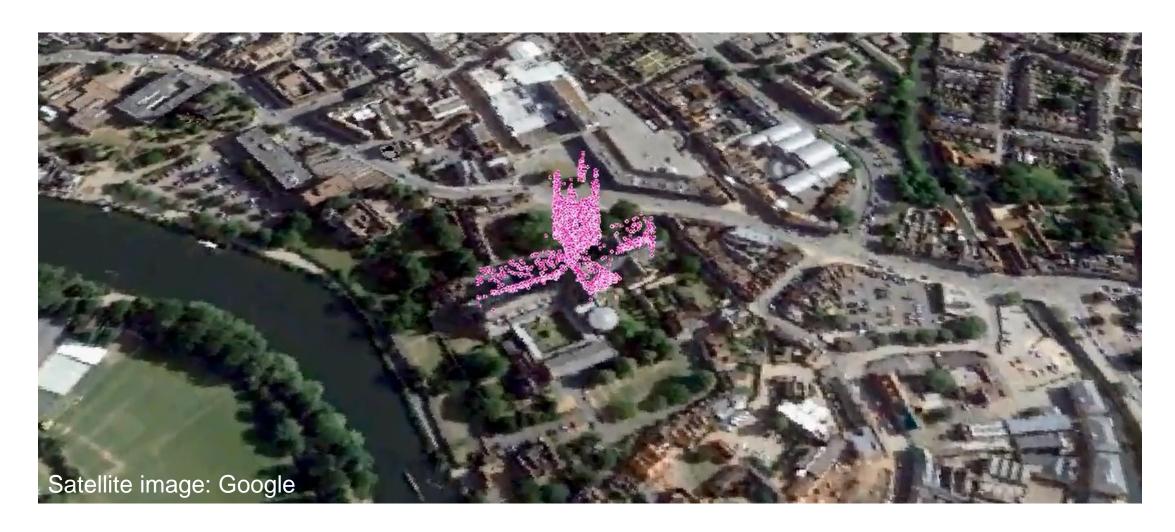








# SDML: Proof of Principle







## Summary

- SDML is real:
  - Funded, current development programme.
  - Flight hardware deliverables.
  - Flight trials ~2021.
- Access to missions / mission enablement / science enablement:
  - SDML + HAPS offers persistent sensing (high-volume data collection).
  - Optical comms mode offers high-volume data egress.
  - HAPS a stepping stone to space-based SDML?
- Science enablement:
  - We invite the scientific community to engage!
- Commercial:
- Optical comms for delivery of internet services into infrastructure-poor regions.
  - Commercial of 3D/2D imagery products.



# QINETIQ

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