



Evolution of Earth Observation With TDI Sensors

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NCEO Annual Conference

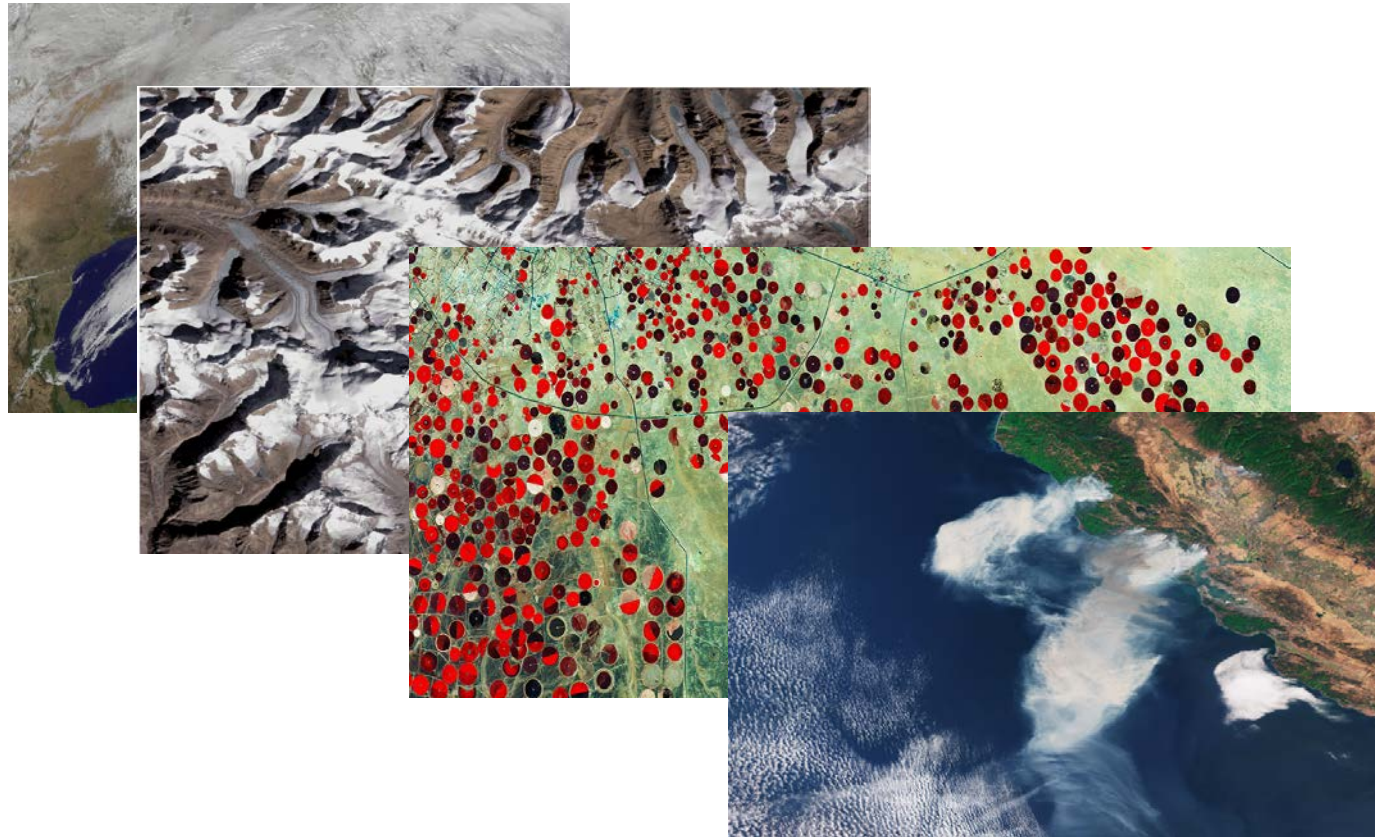
2nd – 5th September 2019

Earth Observation

Applications

+ Earth Observation Programmes have application in a number of fields, including:

- Weather
- Climate Change
- Security/Defence
- Mapping
- Disaster monitoring



Earth Observation

System and Sensor Requirements

+ Cost

- + Reduced Weight + Increased Integration.
- + Constellations → Greater Revisit Time
- + LEO → Reduced Focal Length

+ Spatial Resolution

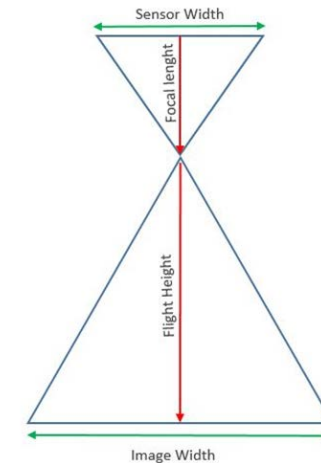
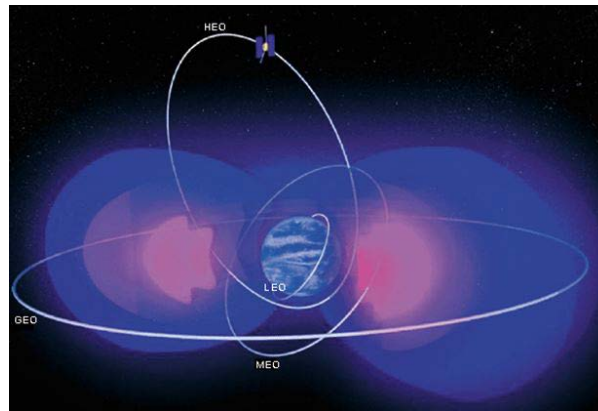
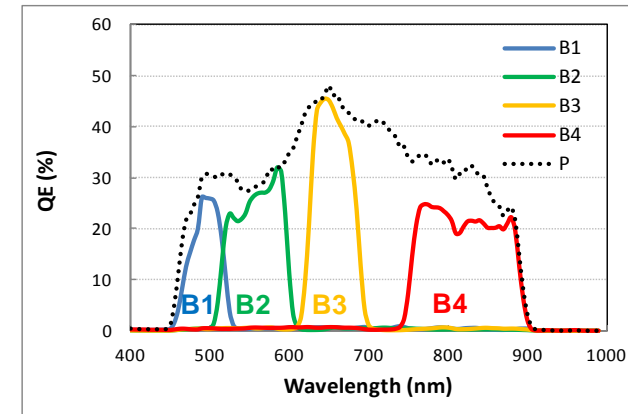
- + Small Pixels → High GSD
- + High Data Rates → High Swath Widths

+ Spectral Resolution

- + Well Defined Channels
- + Optimised Modulation Transfer Function (MTF)
- + Optimised Quantum Efficiency (QE)
- + Strong Out-of-band Rejection

+ Radiation Hardness

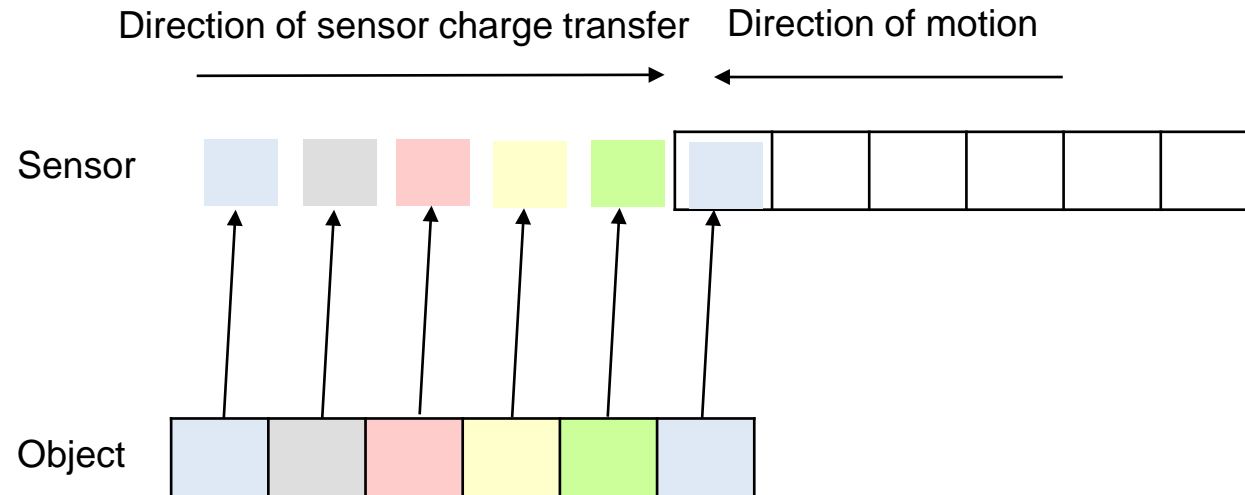
- + Small Interaction Cross Sections
- + Shielding
- + Optimised Operational Modes



Time, Delay and Integration

Principles

- + Time Delay and Integration (TDI) sensors combine integration with charge transfer such that integration occurs as charge is being transferred.



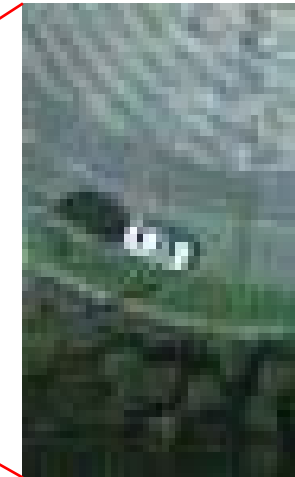
- Charge transfer speed is synchronised with the relative speed between satellite and object of interest.
- Repeated exposure of a scene from pixel to pixel effectively increases optical gain.
- Since charge is summed in the transfer process, SNR improves with number of transfers.
- Integration times on the scale of sensor readout rates make for improved resolution of moving targets compared with staring mode operation

TDI CCDs

- + Charge Coupled Devices inherently support TDI mode of operation through their characteristic charge transfer process.
- + In Low Earth Orbit (LEO), the relative motion between satellite and target is extremely fast. TDI becomes crucial to maintain resolution over staring mode.
- + E.g. Pleiades (e2v) and GeoEye (ITT), both of which boast ~0.3m GSD.

- ✓ Inherent Charge Transfer Capability
- ✓ Low Noise

- ❑ Speed Limited to read out rate
- ❑ Typically Larger Pixels than CMOS
- ❑ Off Chip Video Chain and Clock Generation Electronics
- ❑ High Power Consumption
- ❑ The Above contribute to High Cost



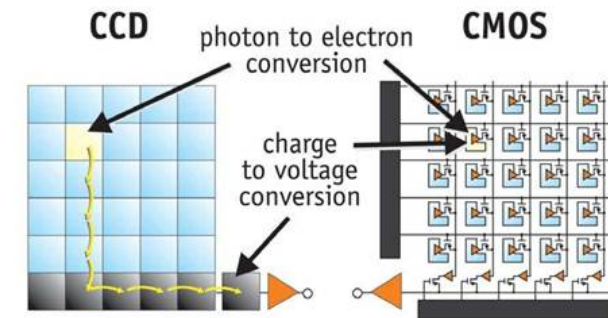
VHR Satellite Comparison



		KompSAT-3A	Pleiades-1A/B	GEOEye-1	WorldView-1
Launch		2015	2011 & 2012	2008	2007
Orbit Height	km	528	695	681	496
Focal Length	m	9	13	13	9
F#		10.75	19.85	12.09	14.67
Pixel Pitch	um	9	13	8	8
Imager Mass	kg	300	200	450	400
Satellite Mass	kg	1100	1015	1955	2500
GSD	m	0.54	0.70	0.41	0.45
GRD	m	0.54	0.85	0.36	0.68
Mission Cost		\$250M	\$425M	\$450M	\$500M

TDI CMOS

- + Minimum possible pixel size capability in CMOS is significantly smaller than for CCDs:
 - + Allows for improved resolution for the same sized telescope → Performance Driver:
 - + Or, a smaller sized telescope for the same resolution → Cost Driver
- + CMOS allows for much higher data rates:
 - + Each pixel has it's own readout → massively parallel read-out compared with CCD
 - + Approx. 0.15Gbit/s for CCD compared with 60Gbit/s for TDI CMOS
 - + Permits higher swath widths without compromising on satellite speed → Higher resolution
- + On chip functionality – Video chain and bias control.
 - + Lower power consumption
 - + Lower voltage requirements reducing the need for high capacity power supplies → reduced mass

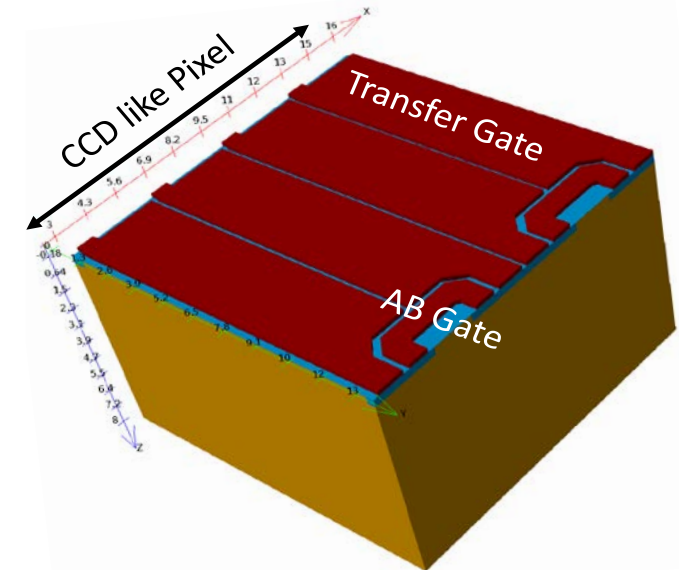
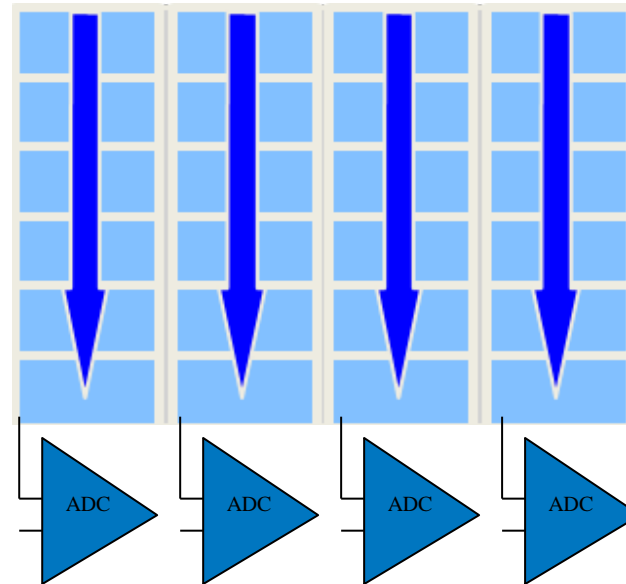


But charge transfer is not inherent to CMOS devices as it is for CCDs.

Optimising TDI CMOS

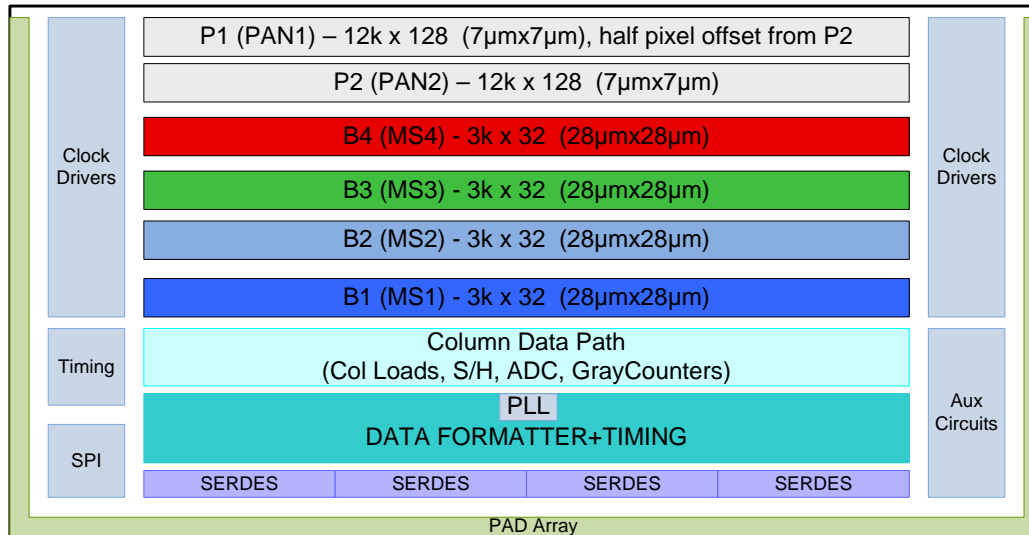
- + One option used is to sum in the digital domain of a staring image (Digital TDI)
 - + Using traditional CMOS architecture, Improvements still to be made around noise, power consumption, memory requirements and MTF.
- + Combining the benefits of CCD and CMOS is a CCD-on-CMOS approach (charge domain CMOS TDI)

- Noiseless charge transfer across CCD-like pixel structure produced on a CMOS process
 - Reduced power consumption
 - Increased radiation hardness
 - Very high data rates
 - High spatial resolution
 - On-Chip Functionality

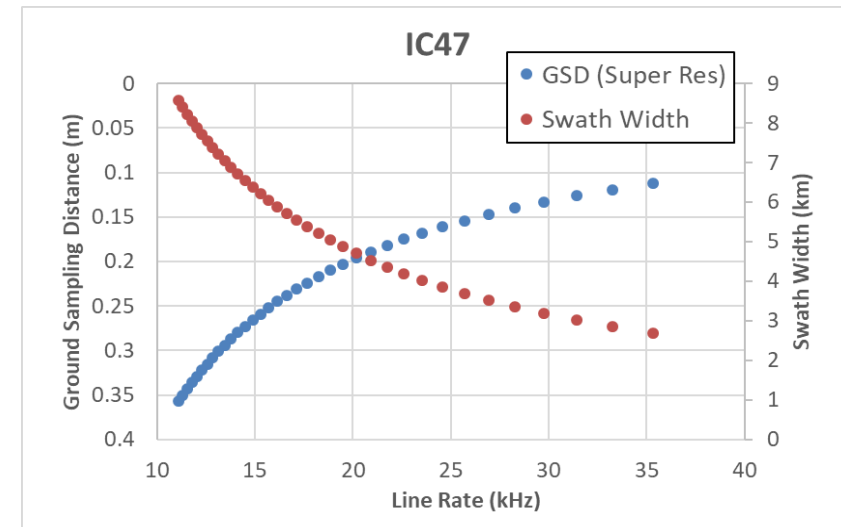


Teledyne Multispectral qTDI CMOS

IC-47 (FSI) and IC-49 (BSI)

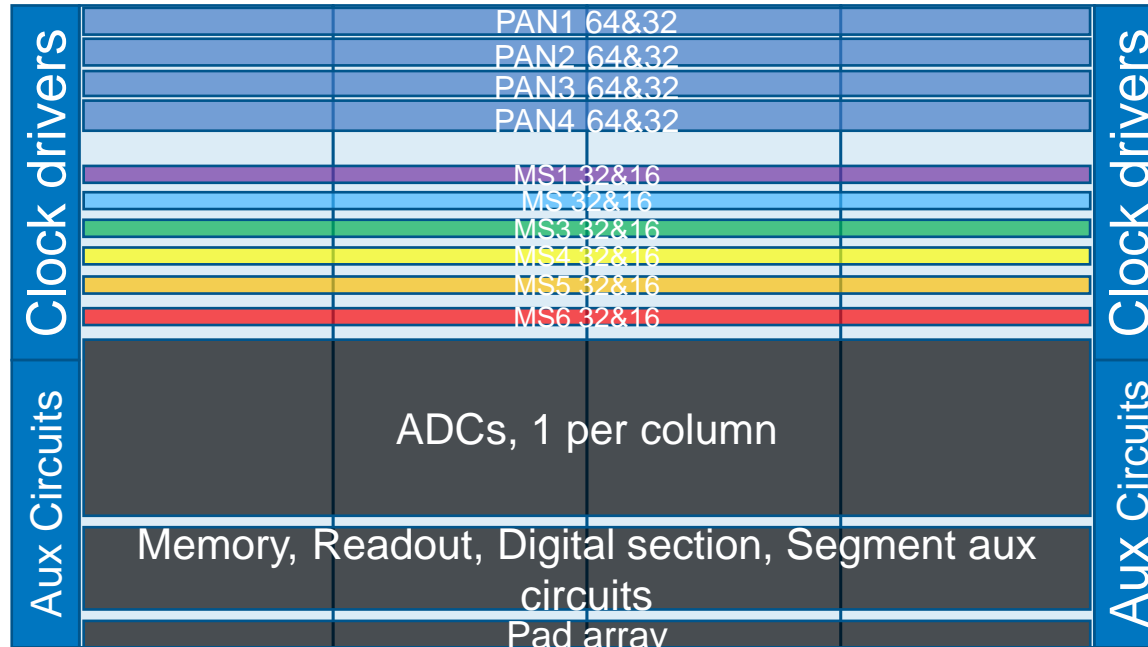


PAN Channels	2 (half pixel offset)
MS Channels	4
Pixel pitch	7µm PAN, 28µm MS
Number of pixels	PAN: 12k columns MS: 3k columns
GSD at max line rate (cm)	11
Swath width at line rate ~10KHz (km)	4.2



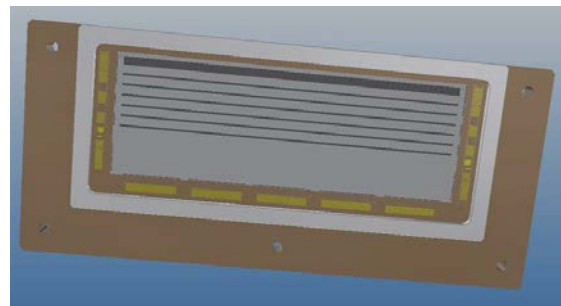
Teledyne Multispectral qTDI CMOS

CIS125 – In Development

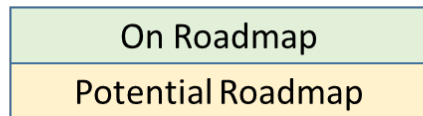
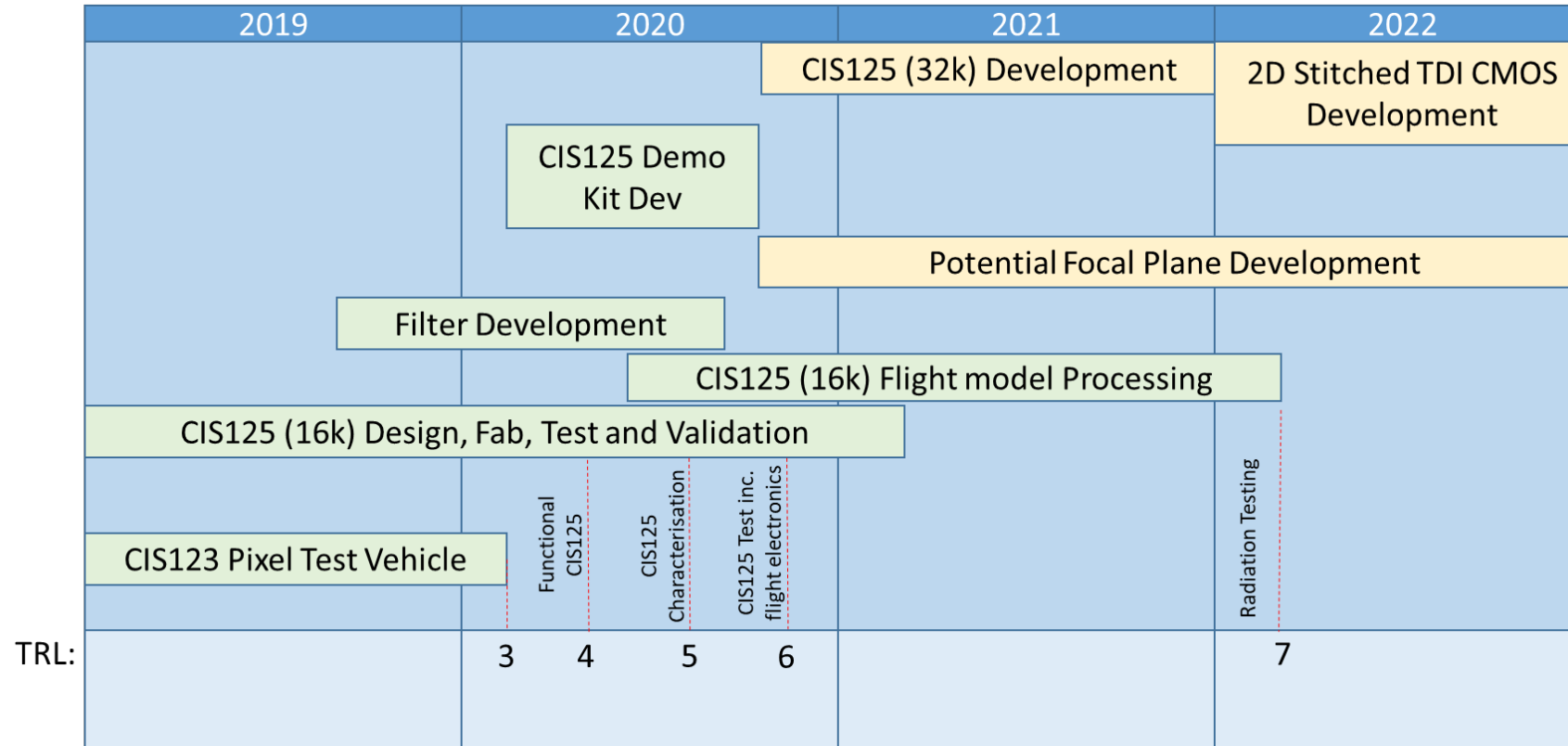


Pan Channels	4
MS Channels	6
Pixel pitch μm	5 μm PAN, 10 μm MS
Number of pixels	PAN: 16k columns MS: 8k columns
GSD at max line rate (cm)^[1]	7
Swath width at line rate ~10KHz (km)	11

^[1]Customisation required to use 2 x PAN only



CIS125 Roadmap





Thank you