SAR Implementation Technology

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Topics

- SAR Instrument Architectures
- Radiator Technologies
- High Power Amplifier Technologies
- Timing & Control Implementation
- Transmit Waveform Generation
- RF Technologies
- Receive Digital Signal Processing



SAR Instrument Architectures



SAR Payload Central Electronics ('Back-End') Architecture



SAR Payload Architecture (with simplest 'Reflector + Horn Feed' Front-End)



SAR Payload Architecture (with 'Reflector + Horn Feed' Front-End plus Calibration paths)



SAR Payload Architecture (Single HPA Planar Array Front-End)





SAR Payload Architecture (Linear Array-Fed Reflector : No Cal paths shown)

All the space you need

EXAMPLE REAL SYSTEM USING THIS ARCHITECTURE : None at present

SAR Payload Architecture (Partially Distributed Front-End : No calibration paths shown)





SAR Payload Architecture (highly distributed phased array)

1 of N columns

EXAMPLE REAL SYSTEM USING THIS ARCHITECTURE : None at present



Radiator Technologies







High Power Amplifier Technologies





High Power Ampifier Technologies

Travelling Wave Tube Amplifier (TWTA)



High Power TWTA or Klystron 100's of Watts to kW's Very high efficiency High cost, large PSU, high mass Need careful control to avoid multipaction

Suitable for <u>single-HPA</u> antennas e.g. ERS-1 & 2, SAR Lupe

ERS-1 TWTA 1.5kW Dual redundant





Gallium Arsenide (GaAs) <15 Watts Well established <30% efficient





ASART/R Module using 10 Watt GaAs devices



Microwave Power Module (MPM) Mini TWTA + Solid-State pre-amplifier Typically ~100 Watts peak

Suitable for <u>partially</u> distributed antennas. but costly to qualify for space use. Better suited to airborne use



Gallium Nitride (GaN) 10's-100's of Watts New technology just coming online High efficiency (30-50%)

Suitable for <u>partially</u> distributed antennas e.g. NovaSAR



All the space you need

SSA

Timing & Control Implementation



Timing & Control Implementation

- At the heart of every radar is a timing 'engine' that controls <u>what</u> happens and when it happens
- Radar 'Timelines' define the activity of each control signal during every different type of 'pulse repetition interval' (PRI)
 - PRI Types
 - Imaging
 - Stripmap
 - ScanSAR includes Tx only and Rx only PRI types for use during subswath changover
 - Calibration Including phase centre stepping, and different CAL paths (e.g. P1,P2,P3)
 - Noise Both 'external' (including LNA and antenna) and internal (excluding LNA and antenna)
- Modes can get complicated very quickly, and so a 'general purpose' approach to the timing engine design is attractive so that it can cope with many different timeline requirements and allows 'late changes' including post-launch



Typical Imaging PRI





Typical Calibration PRI



Timing & Control Implementation

Example implementation scheme :

- Create 'PRI Definition tables' defining (for each PRI type)
- a 'pattern' of the output signals at start of PRI and at each subsequent transition time within the PRI



- Can then define 'sequences of PRIs', and define 'programs' of sequences, to facilitate the overall radar timeline for a mode. For example...
 - CAL/NOISE sequence performs PRIs for P1 Cal, P2 Cal, P3 Cal, Ext Noise, Int Noise IMAGING sequence performs PRIs for Imaging (maybe for Tx H and Tx V as needed)
 - Program performs 1 CAL/NOISE for each phase centre, then 10000 IMAGING, and repeats
- All this functionality is well suited to implementation on an FPGA or an ASIC





Transmit Waveform Generation



Transmit Waveform Generation

- By far the most common waveform used is the linear FM chirp
- A linear sweep from the lowest to the highest frequency (or vice versa) over the pulse duration
- Close to equal power spectral density across the bandwidth used
- Phase is a quadratic





Transmit Waveform Generation Technologies

Arbitrary Waveform Generator (Amplitude)

Surface Acoustic Wave (SAW) Filter



RF Technologies



RF Technologies



Ovenised Resonant Oscillator (Astrium SpHARO)



Individually packaged connectorised RF modules

Minimum integration Maximum access for test & troubleshooting Low NRE cost, high recurring cost High mass and volume



Microstrip Technology Hermetically packaged parts on an Alumina or Duroid substrate with a metal (usually Aluminium) backing Medium level of integration Limited access to selected points in system Medium NRE cost, medium recurring cost



LTCC Technology Very high level of integration Bare die mounted to ceramic substrate and then hermetically sealed Highly limited access to test points High NRE cost Low recurring cost



Multi-Funtion RF Chips Shown is a fractional N PLL including 8 on chip VCOs 'Ultimate' level of integration Very High NRE cost low recurring cost Minimum size/mass/volume



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Receive Digital Signal Processing



Receive Digital Signal Processing

- Most radars use an Analogue to Digital Converter (ADC) to 'capture' the echo signal
- Latest ADC devices are capable of up to 3GHz sampling rate, with up to 12 bit resolution
 - Enables sampling of wide bandwidths
 - Enables sampled signal to be on a carrier
 - Simplifies frequency plan (including through use of Nyquist 2 or 3 regions)
 - Avoids need for vector demodulators which have inherent I/O balance difficulties

• After sampling, it is necessary to perform a number of digital signal processing steps :

- Downconvert to baseband (I/Q)
- Filter and resample to optimise data rate for used bandwidth
- Apply compression algorithm



Some Real System Examples







ASAR on ENVISAT







One of the 20 antenna tiles (structural model)



All the space you need



Deployed Antenna (radiating face)









Stowed antenna

One of the 320 T/R Modules



In-orbit (artists impression)



NovaSAR-S

