### Applications of depth imaging based on time-correlated single-photon counting



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### **Key Collaborators**











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### Introduction

- Photon counting time-of-flight principles
- Scanning photon-counting depth imagers ( $\lambda \sim 850$ nm)
- $\lambda \sim 1550$ nm photon-counting depth imaging using SNSPDs and InGaAs/InP SPAD detectors
- Multiple wavelength depth imaging
- Imaging using arrayed detectors

### Time-of-Flight Measurements using Time-Correlated Single-Photon Counting



JS Massa, AM Wallace, GS Buller, SJ Fancey and AC Walker "Laser depth measurement based on time-correlated single photon counting" Optics Letters, **22**, p543 (1997)

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### **Time-Correlated Single-Photon Counting**



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### Depth Resolution of Time-Correlated Single-Photon Counting



S. Pellegrini, G.S. Buller, J.M. Smith, A.M. Wallace, S. Cova "*Laser-based distance measurement using picosecond resolution time-correlated single-photon counting*" Measurement Science and Technology, **11**, (6) pp712-716 (2000)

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### First Photon-counting Depth Imaging System Indoor, Short-range (1997-2002)

- Short range (< 50 metres)</li>
  size 250 x 200 x 100mm
- λ ~ 850nm, 25MHz rep. rate passively Q-switched semiconductor laser, ~pJ per pulse
- Shallow-junction Si-SPAD.
  Instrumental response ~ 50-75ps FWHM



• Tested in aerospace manufacture, in partnership with Sowerby Research Centre, British Aerospace

J.S.Massa, G.S. Buller, A.C. Walker, S. Cova, M. Umasuthan, and A.M. Wallace *Time-of-Flight Optical Ranging System Using Time-Correlated Single Photon Counting* Applied Optics, **37**, pp7268-7304 (1998)

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### Why Photon Counting Depth Imaging?

### Multi-surface resolution / Imaging through clutter

### Example – cat in a perspex box (2 metres range)



G.S. Buller and A.M. Wallace, "*Recent advances in Ranging and Three-Dimensional imaging using time-correlated single-photon counting*", Journal of Selected Topics in Quantum Electronics, **13**, pp1006-1015, (2007)

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## Why Photon Counting Depth Imaging?

Depth precision at low light levels – few µW's average power example Roman frieze (National Museum of Scotland, Edinburgh)



▶ Depth resolution: 50 µm, Spatial resolution: ~60 µm, Range: 2 metres

G.S. Buller and A.M. Wallace, "*Recent advances in Ranging and Three-Dimensional imaging using time-correlated single-photon counting*", Journal of Selected Topics in Quantum Electronics, **13**, pp1006-1015, (2007)

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### Long-distance scanning depth imaging system

### Transceiver (275×275×170 mm)



Modular system – testbed for new components.

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## Depth imager optical layout for $\lambda \sim 850$ nm



A. McCarthy, R.J. Collins, N.J. Krichel, V. Fernández, A.M. Wallace and G.S. Buller, "Long-range *Time-of-flight Scanning Sensor based on High-speed Time-correlated Single-photon Counting*" Applied Optics, **48**, pp. 6241–6251 (2009)

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### Depth imager optical layout for $\lambda \sim 850$ nm



Galvanometer mirrors steer common transmit and receive beam path

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### Depth imager optical layout for $\lambda \sim 850$ nm



- Galvanometer mirrors steer common transmit and receive beam path.
- Polarising optics split channels

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## Silicon Single-photon Avalanche Diode (SPAD) detectors (500nm < $\lambda$ < 1000nm)





Thin Junction Si-SPAD (active area ~50µm)

Thick Junction Si-SPAD (active area ~180µm)

http://optoelectronics.perkinelmer.com/content/Datasheets/DTS\_SPCMAQRH.pdf http://www.micro-photon-devices.com/

www.single-photon.com

# Mannequin Scan at 325 metres for $\lambda \sim 850$ nm (32 x 128 scan, 2.5 mrad x 5.5 mrad)



# Wavelength considerations - solar background spectrum



Operational wavelength is chosen to take account of detector efficiency, solar background and atmospheric attenuation

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# Superconducting Nanowire Single-Photon Detectors (operate at ~3K, λ ~ 1550nm)



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### NbTiN Superconducting Nanowire **Single-Photon Detectors**

- High single-photon detection efficiency at  $\lambda = 1560$  nm
- Low dark count rate



- Free running (not electrically-gated)
- Low timing jitter with an almost Gaussian temporal profile



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**Gerald Buller** 

### System Temporal Response

Depth profile at a stand-off distance of 910 metres using SNSPD (average laser power < 250μW, λ ~ 1560nm)

#### Dwell time per pixel of 50 ms



#### Dwell time per pixel of **10 ms**



#### Dwell time per pixel of 5 ms



Gerald Buller

A pixel-to-pixel spacing of ~25 mm in x and y

A scan of a retro-reflective flat panel, using a per-pixel acquisition time of 10 ms resulted in a depth uncertainty of 1.1 mm (i.e. timing resolution: 7.3 ps)

A. McCarthy, N.J. Krichel, N.R. Gemmell, X. Ren, M.G. Tanner, S.N. Dorenbos, V. Zwiller, R.H. Hadfield and G.S. Buller, *"Kilometer-range, high resolution depth imaging via 1560 nm wavelength single-photon detection",* Optics Express, **21**, No. 7, pp 8904-8915 (2013)

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### Gated InGaAs/InP SPAD Detector (operates at ~ 230K, λ ~ 1550nm)



Electrically gated InGaAs/InP SPAD module

- Fibre-pigtailed detector
- Active area 25µm diameter
- Cooled to 230K
- 26% single-photon detection efficiency at 16 kcps dark count rate
- Nanosecond detector gating at up to 133MHz (40MHz repetition rate used in these experiments)

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### Single-photon scanning system

Detector	NbTiN SNSPD (resonant cavity)	InGaAs/InP SPAD
Laser	Mode locked fibre laser	Supercontinuum laser
Repetition rate	50MHz	40MHz
Wavelength	1560nm	1550nm
Average optical power	<250µW	<600µW
Detector collection fibre	9µm core diameter	9µm core diameter
Objective lens	500mm FL; 80mm φ	500mm FL; 80mm φ
x-y spatial resolution	50µrad	50µrad
Data acquisition	Picoharp 300	Picoharp 300
Single photon detection efficiency	18%	26%
Dark count rate	1000 counts per second	16,000 counts per second
Temporal response	98ps	144ps
Detector operating temp.	ЗК	230K



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Depth imaging using InGaAs/InP SPAD (Daylight conditions, range 325 metres, average optical power < 600μW, λ ~ 1550nm)



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Plots indicating photon number per pixel range 325 metres, average optical power <  $600\mu$ W,  $\lambda \sim 1550$ nm, pixel acquisition time = 5ms



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# Photon-counting depth imaging at $\lambda \sim 1550$ nm

- Compact Peltier-cooled InGaAs/InP SPAD module used for kilometer range, sub-centimetre resolution depth imaging of non-cooperative targets
- Results comparable with SNSPD under similar operating conditions

Aongus McCarthy, Ximing Ren, Adriano Della Frera, Nathan R. Gemmell, Nils J. Krichel, Carmelo Scarcella, Alessandro Ruggeri, Alberto Tosi, and Gerald S. Buller *"Kilometer-range depth imaging at 1550 nm wavelength using an InGaAs/InP singlephoton avalanche diode detector"* Optics Express, **21**, 19, pp. 22098-22113 (2013)

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# Multiple wavelength depth imaging system



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## Multi-spectral depth analysis on fir tree



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## **Biochemical parameter analysis**

NDVI – Normalized Difference Vegetation Index, measure of photosynthetic efficiency

$$NDVI = \frac{R_{\lambda = 570nm} - R_{\lambda = 531nm}}{R_{\lambda = 570nm} + R_{\lambda = 531nm}}$$

**PRI** – Photochemical Reflectance Index, measure of biomass

$$\mathbf{PRI} = \frac{\mathbf{R}_{\lambda = 780 \text{ nm}} - \mathbf{R}_{\lambda = 670 \text{ nm}}}{\mathbf{R}_{\lambda = 780 \text{ nm}} + \mathbf{R}_{\lambda = 670 \text{ nm}}}$$



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# **Biochemical parameter analysis**



The LIDAR data is analysed using the Reversible Jump Markov Chain Monte Carlo to give a layer-by-layer analysis of tree at each wavelength – NDVI is shown in green on right. Laboratory analysis of same tree is shown for nine selected layers (yellow)

A.M. Wallace, A. McCarthy, C.J. Nichol, X. Ren, S. Morak, D. Martinez-Ramirez, I.H. Woodhouse, and G.S. Buller, *"Design and Evaluation of Multispectral LiDAR for the Recovery of Arboreal Parameters"*, IEEE Transactions on Geosciences and Remote Sensing (in press).

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## Conclusions

- Compact Peltier-cooled InGaAs/InP SPAD module used for kilometre range, sub-centimetre resolution depth imaging of non-cooperative targets at λ ~ 1550nm. Results comparable with SNSPD under similar operating conditions.
- Remote measurements on tree samples indicate biochemical parameters can be ascertained as a function of tree height. Current experiments are being tested at 300-900 metres range
- Arrayed SPADs used in conjunction with scanner to obtain highresolution images. Challenge is non-cooperative targets at kilometre range.